## Semi-separated pair decomposition \&

low-quality approximate nearest neighbors

## Motivation: low-quality approximate nearest neighbors

1. (Compressed) quadtree returns $(1+\varepsilon)$-approximate nearest neighbor of $q$ in time $O\left(1 / \varepsilon^{d}+\log (1 / r)\right)$ time, where $r=d(q, n n(q))$


## Motivation: low-quality approximate nearest neighbors

1. (Compressed) quadtree returns $(1+\varepsilon)$-approximate nearest neighbor of $q$ in time $O\left(1 / \varepsilon^{d}+\log (1 / r)\right)$ time, where $r=d(q, n n(q))$

Problem: $r$ can be arbitrary small.


## Motivation: low-quality approximate nearest neighbors

1. (Compressed) quadtree returns $(1+\varepsilon)$-approximate nearest neighbor of $q$ in time $O\left(1 / \varepsilon^{d}+\log (1 / r)\right)$ time, where $r=d(q, n n(q))$ Problem: $r$ can be arbitrary small.
2. If we can compute an $O(n)$-ANN $p$, then we can


## Motivation: low-quality approximate nearest neighbors

1. (Compressed) quadtree returns $(1+\varepsilon)$-approximate nearest neighbor of $q$ in time $O\left(1 / \varepsilon^{d}+\log (1 / r)\right)$ time, where $r=d(q, n n(q))$

## Problem: $r$ can be arbitrary small.

2. If we can compute an $O(n)$-ANN $p$, then we can (a) Find the $O(1)$ cells of $G_{\alpha}$ that could contain $n n(q)$, where $\alpha=\|p-q\|$ rounded down to the next power $2^{-i}$


## Motivation: low-quality approximate nearest neighbors

1. (Compressed) quadtree returns $(1+\varepsilon)$-approximate nearest neighbor of $q$ in time $O\left(1 / \varepsilon^{d}+\log (1 / r)\right)$ time, where $r=d(q, n n(q))$

## Problem: $r$ can be arbitrary small.

2. If we can compute an $O(n)$-ANN $p$, then we can (a) Find the $O(1)$ cells of $G_{\alpha}$ that could contain $n n(q)$, where $\alpha=\|p-q\|$ rounded down to the next power $2^{-i}$

(b) Use (1.), starting from these cells

## Motivation: low-quality approximate nearest neighbors

1. (Compressed) quadtree returns $(1+\varepsilon)$-approximate nearest neighbor of $q$ in time $O\left(1 / \varepsilon^{d}+\log (1 / r)\right)$ time, where $r=d(q, n n(q))$

## Problem: $r$ can be arbitrary small.

2. If we can compute an $O(n)$-ANN $p$, then we can
(a) Find the $O(1)$ cells of $G_{\alpha}$ that could contain $n n(q)$,
 where $\alpha=\|p-q\|$ rounded down to the next power $2^{-i}$
(b) Use (1.), starting from these cells

$$
\text { Now, } 1 / r=O(n) \text { relative to } \alpha=O(n r)
$$

## Motivation: low-quality approximate nearest neighbors

1. (Compressed) quadtree returns $(1+\varepsilon)$-approximate nearest neighbor of $q$ in time $O\left(1 / \varepsilon^{d}+\log (1 / r)\right)$ time, where $r=d(q, n n(q))$

## Problem: $r$ can be arbitrary small.

2. If we can compute an $O(n)$-ANN $p$, then we can
(a) Find the $O(1)$ cells of $G_{\alpha}$ that could contain $n n(q)$,
 where $\alpha=\|p-q\|$ rounded down to the next power $2^{-i}$
(b) Use (1.), starting from these cells

$$
\text { Now, } 1 / r=O(n) \text { relative to } \alpha=O(n r)
$$

This requires $O(n)$-ANN $\rightarrow$ today

## Motivation 2: The weight of the WSPD

Well-separated pair decomposition: Cover all pairs of points by $1 / \varepsilon$-well-separated pairs of point sets $\{A, B\}$ :


## Motivation 2: The weight of the WSPD

Well-separated pair decomposition: Cover all pairs of points by $1 / \varepsilon$-well-separated pairs of point sets $\{A, B\}$ :

good: $O(n)$ pairs are enough (size of WSPD)

## Motivation 2: The weight of the WSPD

Well-separated pair decomposition: Cover all pairs of points by $1 / \varepsilon$-well-separated pairs of point sets $\{A, B\}$ :

good: $O(n)$ pairs are enough (size of WSPD)
but: might require $\sum_{i}\left|A_{i}\right|+\left|B_{i}\right|=\Theta\left(n^{2}\right)$ (weight of WSPD)

## Overview

Semi-separated pair decomposition (SSPD)
Ring separator tree: $n$-semi-separated pair decomposition
Ring separator tree: $O(n)$-ANN
$(1 / \varepsilon)$-semi-separated pair decomposition

## Semi-Separated Pairs


$1 / \varepsilon$-well-separated pair: $\max \left(r_{A}, r_{B}\right) \leq \varepsilon d(A, B)$

## Semi-Separated Pairs


$1 / \varepsilon$-well-separated pair: $\max \left(r_{A}, r_{B}\right) \leq \varepsilon d(A, B)$
$1 / \varepsilon$-semi-separated pair: $\min \left(r_{A}, r_{B}\right) \leq \varepsilon d(A, B)$

## Semi-Separated Pairs


$1 / \varepsilon$-well-separated pair: $\max \left(r_{A}, r_{B}\right) \leq \varepsilon d(A, B)$
$1 / \varepsilon$-semi-separated pair: $\min \left(r_{A}, r_{B}\right) \leq \varepsilon d(A, B)$

## Semi-Separated Pairs



## ring separator:

- ball $b=b(p, r)$ containing $\geq n / c_{1}$ points
- no point in $b(p, r(1+1 / n)) \backslash b$
- $\geq n / c_{2}$ points outside $b(p, 2 r)$


## Computing a ring separator

1. Compute $b=b(p, \alpha)$ : 2-approximation of smallest ball containing $n / c_{1}$ points ( $c_{1}$ to be determined later)

## Computing a ring separator

1. Compute $b=b(p, \alpha)$ : 2-approximation of smallest ball containing $n / c_{1}$ points ( $c_{1}$ to be determined later)

## Computing a ring separator

1. Compute $b=b(p, \alpha)$ : 2-approximation of smallest ball containing $n / c_{1}$ points ( $c_{1}$ to be determined later)
2. Hash the points in $b(p, e \cdot \alpha) \backslash b$ into rings $r_{i}:=b_{i} \backslash b_{i-1}$, where $b_{i}:=b\left(p, r(1+1 / n)^{i}, b_{0}=b\right.$


## Computing a ring separator

1. Compute $b=b(p, \alpha)$ : 2-approximation of smallest ball containing $n / c_{1}$ points ( $c_{1}$ to be determined later)
2. Hash the points in $b(p, e \cdot \alpha) \backslash b$ into rings $r_{i}:=b_{i} \backslash b_{i-1}$, where $b_{i}:=b\left(p, r(1+1 / n)^{i}, b_{0}=b\right.$
3. Find empty ring $r_{i}$ and return $b_{i-1}$


## Computing a ring separator

1. Compute $b=b(p, \alpha)$ : 2-approximation of smallest ball containing $n / c_{1}$ points ( $c_{1}$ to be determined later)
2. Hash the points in $b(p, e \cdot \alpha) \backslash b$ into rings $r_{i}:=b_{i} \backslash b_{i-1}$, where $b_{i}:=b\left(p, r(1+1 / n)^{i}, b_{0}=b\right.$
3. Find empty ring $r_{i}$ and return $b_{i-1}$

Quiz What is the (expected) worst-case running time of the algorithm?
A $\Theta(n)$
B $\Theta(n \log n)$
C $\Theta\left(n^{2}\right)$

## Computing a ring separator

1. Compute $b=b(p, \alpha)$ : 2-approximation of smallest ball containing $n / c_{1}$ points ( $c_{1}$ to be determined later)
2. Hash the points in $b(p, e \cdot \alpha) \backslash b$ into rings $r_{i}:=b_{i} \backslash b_{i-1}$, where $b_{i}:=b\left(p, r(1+1 / n)^{i}, b_{0}=b\right.$
3. Find empty ring $r_{i}$ and return $b_{i-1}$

Quiz What is the (expected) worst-case running time of the algorithm?
A $\Theta(n)$
B $\Theta(n \log n)$
C $\Theta\left(n^{2}\right)$

Correctness

## Correctness

$b=b(p, \alpha)$ 2-approx. smallest ball containing $n / c_{1}$ points


## Correctness

$b=b(p, \alpha) 2$-approx. smallest ball containing $n / c_{1}$ points
$\Rightarrow$ no disk of radius $r=\alpha / 2$ contains more than $n / c_{1}$ points


## Correctness

$b=b(p, \alpha)$ 2-approx. smallest ball containing $n / c_{1}$ points
$\Rightarrow$ no disk of radius $r=\alpha / 2$ contains more than $n / c_{1}$ points $b(p, 8 \alpha)$ can be covered by $c=O(1)$ disks of radius $\alpha / 2$

## Correctness

$b=b(p, \alpha)$ 2-approx. smallest ball containing $n / c_{1}$ points
$\Rightarrow$ no disk of radius $r=\alpha / 2$ contains more than $n / c_{1}$ points $b(p, 8 \alpha)$ can be covered by $c=O(1)$ disks of radius $\alpha / 2$

Choose: $c_{1}:=3 c$


## Correctness

$b=b(p, \alpha)$ 2-approx. smallest ball containing $n / c_{1}$ points
$\Rightarrow$ no disk of radius $r=\alpha / 2$ contains more than $n / c_{1}$ points $b(p, 8 \alpha)$ can be covered by $c=O(1)$ disks of radius $\alpha / 2$
Choose: $c_{1}:=3 c$
$b(p, 8 \alpha)$ contains $\leq c \frac{n}{3 c}<n / 2$ points


## Correctness

$b=b(p, \alpha) 2$-approx. smallest ball containing $n / c_{1}$ points
$\Rightarrow$ no disk of radius $r=\alpha / 2$ contains more than $n / c_{1}$ points
$b(p, 8 \alpha)$ can be covered by $c=O(1)$ disks of radius $\alpha / 2$
Choose: $c_{1}:=3 c$
$b(p, 8 \alpha)$ contains $\leq c \frac{n}{3 c}<n / 2$ points

$r_{i}:=b_{i} \backslash b_{i-1}$, are $n$ ranges in
$b_{n}=b\left(p, \alpha(1+1 / n)^{n}\right) \subset b(p, \alpha e) \subset b(p, 8 \alpha)$

## Correctness

$b=b(p, \alpha) 2$-approx. smallest ball containing $n / c_{1}$ points
$\Rightarrow$ no disk of radius $r=\alpha / 2$ contains more than $n / c_{1}$ points
$b(p, 8 \alpha)$ can be covered by $c=O(1)$ disks of radius $\alpha / 2$
Choose: $c_{1}:=3 c$
$b(p, 8 \alpha)$ contains $\leq c \frac{n}{3 c}<n / 2$ points

$r_{i}:=b_{i} \backslash b_{i-1}$, are $n$ ranges in
$b_{n}=b\left(p, \alpha(1+1 / n)^{n}\right) \subset b(p, \alpha e) \subset b(p, 8 \alpha)$
pigeonhole principle: There is an empty range $r_{i}$

## Correctness

$b=b(p, \alpha)$ 2-approx. smallest ball containing $n / c_{1}$ points
$\Rightarrow$ no disk of radius $r=\alpha / 2$ contains more than $n / c_{1}$ points
$b(p, 8 \alpha)$ can be covered by $c=O(1)$ disks of radius $\alpha / 2$
Choose: $c_{1}:=3 c$
$b(p, 8 \alpha)$ contains $\leq c \frac{n}{3 c}<n / 2$ points

$r_{i}:=b_{i} \backslash b_{i-1}$, are $n$ ranges in
$b_{n}=b\left(p, \alpha(1+1 / n)^{n}\right) \subset b(p, \alpha e) \subset b(p, 8 \alpha)$
pigeonhole principle: There is an empty range $r_{i}$
$b_{i-1}$ contains $n / c_{1}$ points, $r_{i}$ empty,
$>n / 2$ points outside of ball of twice the radius

## Ring Separator tree

A binary tree $T$ having the points of $P$ as leaves is a $t$-ring tree for $P$ iff:

## Ring Separator tree

A binary tree $T$ having the points of $P$ as leaves is a $t$-ring tree for $P$ iff:

- Every node $v \in T$ with corresponding subset $P_{v} \subset P$ is associated with a 'ring' that separates the points of $P_{v}$ into two sets



## Ring Separator tree

A binary tree $T$ having the points of $P$ as leaves is a $t$-ring tree for $P$ iff:

- Every node $v \in T$ with corresponding subset $P_{v} \subset P$ is associated with a 'ring' that separates the points of $P_{v}$ into two sets
- The interior of the ring has no points inside it



## Ring Separator tree

A binary tree $T$ having the points of $P$ as leaves is a $t$-ring tree for $P$ iff:

- Every node $v \in T$ with corresponding subset $P_{v} \subset P$ is associated with a 'ring' that separates the points of $P_{v}$ into two sets
- The interior of the ring has no points inside it
- The interior of the ring is of width $t$



## Ring Separator tree

A binary tree $T$ having the points of $P$ as leaves is a $t$-ring tree for $P$ iff:

- Every node $v \in T$ with corresponding subset $P_{v} \subset P$ is associated with a 'ring' that separates the points of $P_{v}$ into two sets
- The interior of the ring has no points inside it
- The interior of the ring is of width $t$

Apply algorithm for ring separator recursively


## Ring Separator tree

A binary tree $T$ having the points of $P$ as leaves is a $t$-ring tree for $P$ iff:

- Every node $v \in T$ with corresponding subset $P_{v} \subset P$ is associated with a 'ring' that separates the points of $P_{v}$ into two sets
- The interior of the ring has no points inside it
- The interior of the ring is of width $t$

Apply algorithm for ring separator recursively
Result: A $\frac{1}{n}$-ring separator tree
A $n$-semi-separated pair decomposition of weight $\Theta(n \log n)$


## Overview

Semi-separated pair decomposition (SSPD)
Ring separator tree: $n$-semi-separated pair decomposition
Ring separator: $O(n)$-ANN
$(1 / \varepsilon)$-semi-separated pair decomposition

## Ring Separator Tree

For every node $v$ we ensure:
There is a ball $b_{v}=b\left(c_{v}, r_{v}\right)$ s.t. all points of $P_{v}^{\text {in }}=P_{v} \cap b_{v}$ are in one child of $v$ (the inner child)

All other points of $P_{v}$ are outside $b\left(c_{v},(1+t) r_{v}\right)$ and stored in the other child (the outer child)


## Ring Separator Tree

For every node $v$ we ensure:
There is a ball $b_{v}=b\left(c_{v}, r_{v}\right)$ s.t. all points of $P_{v}^{\text {in }}=P_{v} \cap b_{v}$ are in one child of $v$ (the inner child)

All other points of $P_{v}$ are outside $b\left(c_{v},(1+t) r_{v}\right)$ and stored in the other child (the outer child)

Store an arbitrary $r e p_{v} \in P_{v}^{\text {in }}$ in $v$


ANN search procedure

Given query point $q$ :


ANN search procedure

Given query point $q$ :
$v=\operatorname{root}$ of $T, r=\infty$


ANN search procedure

Given query point $q$ :
$v=$ root of $T, r=\infty$
while $v$ is not a leaf:

$$
r=\min \left(r,\left\|q-r e p_{v}\right\|\right)
$$

## ANN search procedure

Given query point $q$ :
$v=$ root of $T, r=\infty$
while $v$ is not a leaf:

$$
\begin{aligned}
& r=\min \left(r,\left\|q-r e p_{v}\right\|\right) \\
& r_{m i d}=(1+t / 2) r_{v}
\end{aligned}
$$



## ANN search procedure

Given query point $q$ :
$v=\operatorname{root}$ of $T, r=\infty$
while $v$ is not a leaf:

$$
\begin{aligned}
& r=\min \left(r,\left\|q-r e p_{v}\right\|\right) \\
& r_{m i d}=(1+t / 2) r_{v} \\
& \text { if }\left\|q-c_{v}\right\| \leq r_{m i d} \text { then } \\
& v=\text { inner child of } v \\
& \text { else } \\
& v=\text { outer child of } v
\end{aligned}
$$

return $r$

## ANN search procedure

Given query point $q$ :
$v=$ root of $T, r=\infty$
while $v$ is not a leaf:

$$
\begin{aligned}
& r=\min \left(r,\left\|q-r e p_{v}\right\|\right) \\
& r_{m i d}=(1+t / 2) r_{v} \\
& \text { if }\left\|q-c_{v}\right\| \leq r_{m i d} \text { then } \\
& v=\text { inner child of } v \\
& \text { else } \\
& v=\text { outer child of } v
\end{aligned}
$$

return $r$


## ANN search procedure

Given query point $q$ :
$v=$ root of $T, r=\infty$
while $v$ is not a leaf:

$$
\begin{aligned}
& r=\min \left(r,\left\|q-r e p_{v}\right\|\right) \\
& r_{m i d}=(1+t / 2) r_{v} \\
& \text { if }\left\|q-c_{v}\right\| \leq r_{m i d} \text { then } \\
& v=\text { inner child of } v \\
& \text { else }
\end{aligned}
$$

$v=$ outer child of $v$
return $r$


## ANN search procedure

Given query point $q$ :
$v=$ root of $T, r=\infty$
while $v$ is not a leaf:

$$
\begin{aligned}
& r=\min \left(r,\left\|q-r e p_{v}\right\|\right) \\
& r_{m i d}=(1+t / 2) r_{v} \\
& \text { if }\left\|q-c_{v}\right\| \leq r_{m i d} \text { then } \\
& v=\text { inner child of } v \\
& \text { else } \\
& v=\text { outer child of } v
\end{aligned}
$$

return $r$

## ANN search procedure

Given query point $q$ :
$v=$ root of $T, r=\infty$
while $v$ is not a leaf:

$$
\begin{aligned}
& r=\min \left(r,\left\|q-r e p_{v}\right\|\right) \\
& r_{m i d}=(1+t / 2) r_{v} \\
& \text { if }\left\|q-c_{v}\right\| \leq r_{m i d} \text { then } \\
& v=\text { inner child of } v \\
& \text { else } \\
& v=\text { outer child of } v
\end{aligned}
$$

return $r$

## ANN search procedure

Given query point $q$ :
$v=$ root of $T, r=\infty$
while $v$ is not a leaf:

$$
\begin{aligned}
& r=\min \left(r,\left\|q-r e p_{v}\right\|\right) \\
& r_{m i d}=(1+t / 2) r_{v} \\
& \text { if }\left\|q-c_{v}\right\| \leq r_{m i d} \text { then } \\
& v=\text { inner child of } v \\
& \text { else } \\
& v=\text { outer child of } v
\end{aligned}
$$

return $r$

## ANN search procedure

Given query point $q$ :
$v=$ root of $T, r=\infty$
while $v$ is not a leaf:

$$
\begin{aligned}
& r=\min \left(r,\left\|q-r e p_{v}\right\|\right) \\
& r_{m i d}=(1+t / 2) r_{v} \\
& \text { if }\left\|q-c_{v}\right\| \leq r_{m i d} \text { then } \\
& v=\text { inner child of } v \\
& \text { else } \\
& v=\text { outer child of } v
\end{aligned}
$$

return $r$

## ANN search procedure

Given query point $q$ :
$v=$ root of $T, r=\infty$
while $v$ is not a leaf:

$$
\begin{aligned}
& r=\min \left(r,\left\|q-r e p_{v}\right\|\right) \\
& r_{m i d}=(1+t / 2) r_{v} \\
& \text { if }\left\|q-c_{v}\right\| \leq r_{m i d} \text { then } \\
& v=\text { inner child of } v \\
& \text { else } \\
& v=\text { outer child of } v
\end{aligned}
$$

return $r$

Intuition of correctness

Case distinction:


Intuition of correctness

Case distinction:
1.) $q$ in $b_{v}$


## Intuition of correctness

Case distinction:
1.) $q$ in $b_{v} \rightarrow$ points outside of $b_{v}$ too far away
(to invalidate $\operatorname{rep}_{v}$ as $1 / t$-ANN)

## Intuition of correctness

## Case distinction:

1.) $q$ in $b_{v} \rightarrow$ points outside of $b_{v}$ too far away (to invalidate $r e p_{v}$ as $1 / t$-ANN)
2.) $q$ outside enlarged $b_{v}$


## Intuition of correctness

Case distinction:
1.) $q$ in $b_{v} \rightarrow$ points outside of $b_{v}$ too far away (to invalidate $r e p_{v}$ as $1 / t$-ANN)
2.) $q$ outside enlarged $b_{v}$
$\rightarrow$ points inside $b_{v}$ all have approximately the same distance to $q$


## Intuition of correctness

Case distinction:
1.) $q$ in $b_{v} \rightarrow$ points outside of $b_{v}$ too far away (to invalidate $r e p_{v}$ as $1 / t$-ANN)
2.) $q$ outside enlarged $b_{v}$
$\rightarrow$ points inside $b_{v}$ all have approximately the same distance to $q$
$\rightarrow$ sufficient to test 1 point in $b_{v}:$ rep $_{v}$


## Intuition of correctness

Case distinction:
1.) $q$ in $b_{v} \rightarrow$ points outside of $b_{v}$ too far away (to invalidate $r e p_{v}$ as $1 / t$-ANN)
2.) $q$ outside enlarged $b_{v}$
$\rightarrow$ points inside $b_{v}$ all have approximately the same distance to $q$
$\rightarrow$ sufficient to test 1 point in $b_{v}$ : rep
3.) $q$ in ring


## Intuition of correctness

Case distinction:
1.) $q$ in $b_{v} \rightarrow$ points outside of $b_{v}$ too far away (to invalidate $r e p_{v}$ as $1 / t$-ANN)
2.) $q$ outside enlarged $b_{v}$
$\rightarrow$ points inside $b_{v}$ all have approximately the same distance to $q$
$\rightarrow$ sufficient to test 1 point in $b_{v}:$ rep $_{v}$

## 3.) $q$ in ring

1.) or 2.) applies with slightly worse bounds


## Correctness

The algorithm finds a $(1+4 / t)$-ANN.

## Correctness

The algorithm finds a $(1+4 / t)$-ANN.
Node $w$ of $T$ : Last node on search path such that $n n(q) \in P_{w}$.

## Correctness

The algorithm finds a $(1+4 / t)$-ANN.
Node $w$ of $T$ : Last node on search path such that $n n(q) \in P_{w}$.
Case 1: $n n(q) \in P_{o u t}^{w}$ but $\left\|q-c_{w}\right\| \leq r_{w}(1+1 / t)$


## Correctness

The algorithm finds a $(1+4 / t)$-ANN.
Node $w$ of $T$ : Last node on search path such that $n n(q) \in P_{w}$.
Case 1: $n n(q) \in P_{o u t}^{w}$ but $\left\|q-c_{w}\right\| \leq r_{w}(1+1 / t)$

$$
\frac{\left\|q-r e p_{w}\right\|}{\|q-n n(q)\|} \leq \frac{(2+t / 2) r_{w}}{(t / 2) r_{w}} \leq 1+4 / t
$$



## Correctness

The algorithm finds a $(1+4 / t)$-ANN.
Node $w$ of $T$ : Last node on search path such that $n n(q) \in P_{w}$.
Case 1: $n n(q) \in P_{o u t}^{w}$ but $\left\|q-c_{w}\right\| \leq r_{w}(1+1 / t)$

$$
\frac{\left\|q-r e p_{w}\right\|}{\|q-n n(q)\|} \leq \frac{(2+t / 2) r_{w}}{(t / 2) r_{w}} \leq 1+4 / t
$$

Case 2: $n n(q) \in P_{i n}^{w}$ but $\left\|q-c_{w}\right\| \geq r_{w}(1+1 / t)$


## Correctness

The algorithm finds a $(1+4 / t)$-ANN.
Node $w$ of $T$ : Last node on search path such that $n n(q) \in P_{w}$.
Case 1: $n n(q) \in P_{o u t}^{w}$ but $\left\|q-c_{w}\right\| \leq r_{w}(1+1 / t)$

$$
\frac{\left\|q-r e p_{w}\right\|}{\|q-n n(q)\|} \leq \frac{(2+t / 2) r_{w}}{(t / 2) r_{w}} \leq 1+4 / t
$$

Case 2: $n n(q) \in P_{i n}^{w}$ but $\left\|q-c_{w}\right\| \geq r_{w}(1+1 / t)$

$$
\frac{\left\|q-r e p_{w}\right\|}{\|q-n n(q)\|} \leq \frac{\|q-n n(q)\|+\left\|n n(q)-r e p_{w}\right\|}{\|q-n n(q)\|}
$$



## Correctness

The algorithm finds a $(1+4 / t)$-ANN.
Node $w$ of $T$ : Last node on search path such that $n n(q) \in P_{w}$.
Case 1: $n n(q) \in P_{o u t}^{w}$ but $\left\|q-c_{w}\right\| \leq r_{w}(1+1 / t)$

$$
\frac{\left\|q-r e p_{w}\right\|}{\|q-n n(q)\|} \leq \frac{(2+t / 2) r_{w}}{(t / 2) r_{w}} \leq 1+4 / t
$$

Case 2: $n n(q) \in P_{i n}^{w}$ but $\left\|q-c_{w}\right\| \geq r_{w}(1+1 / t)$

$$
\begin{aligned}
\frac{\left\|q-r e p_{w}\right\|}{\|q-n n(q)\|} & \leq \frac{\|q-n n(q)\|+\left\|n n(q)-r e p_{w}\right\|}{\|q-n n(q)\|} \\
& \leq 1+\frac{2 r_{w}}{(t / 2) r_{w}}=1+4 / t
\end{aligned}
$$

## Overview

Semi-separated pair decomposition (SSPD)
Ring separator: $n$-semi-separated pair decomposition
Ring separator tree: $O(n)$-ANN
$(1 / \varepsilon)$-semi-separated pair decomposition - brief sketch

## (1/ $)$-Semi-Separated Pairs



## ring separator:

- ball $b=b(p, r)$ containing $\geq n / c_{1}$ points
- no point in $b(p, r(1+1 / n)) \backslash b$
- $\geq n / c_{2}$ points outside $b(p, 2 r)$


## (1/ $)$-Semi-Separated Pairs



## ring separator:

- ball $b=b(p, r)$ containing $\geq n / c_{1}$ points
- no point in $b(p, r(1+1 / n)) \backslash b$
- $\geq n / c_{2}$ points outside $b(p, 2 r)$


## (1/ $)$-Semi-Separated Pairs



## ring separator:

- ball $b=b(p, r)$ containing $\geq n / c_{1}$ points
- no point in $b(p, r(1+1 / n)) \backslash b$
- $\geq n / c_{2}$ points outside $b(p, 2 r)$


## (1/ $)$-Semi-Separated Pairs



## ring separator:

- ball $b=b(p, r)$ containing $\geq n / c_{1}$ points
- no point in $b(p, r(1+1 / n)) \backslash b$
- $\geq n / c_{2}$ points outside $b(p, 2 r)$


## (1/ $)$-Semi-Separated Pairs



## ring separator:

- ball $b=b(p, r)$ containing $\geq n / c_{1}$ points
- no point in $b(p, r(1+1 / n)) \backslash b$
- $\geq n / c_{2}$ points outside $b(p, 2 r)$

Dealing with $P_{\text {in }}, P_{\text {out }}$ (sketch)


## Dealing with $P_{\text {in }}, P_{\text {out }}$ (sketch)



## Dealing with $P_{\text {in }}, P_{\text {out }}$ (sketch)



## Dealing with $P_{\text {in }}, P_{\text {out }}$ (sketch)



$$
\begin{aligned}
& \operatorname{diam}\left(P_{\text {in }} \cup P_{\text {out }}\right) \leq 2 r / \varepsilon \\
& \ell:=\min _{p \in P_{\text {in }}, q \in P_{\text {out }}}\|p-q\| \geq r / n
\end{aligned}
$$

$$
\text { snap points to a grid } G_{\alpha} \text { with } \alpha=\varepsilon \ell / 10
$$

## Dealing with $P_{\text {in }}, P_{\text {out }}$ (sketch)


$\operatorname{diam}\left(P_{\text {in }} \cup P_{\text {out }}\right) \leq 2 r / \varepsilon$
$\ell:=\min _{p \in P_{\text {in }}, q \in P_{\text {out }}}\|p-q\| \geq r / n$
snap points to a grid $G_{\alpha}$ with $\alpha=\varepsilon \ell / 10$
Use WSPD algorithm for bounded spread to compute WSPs with $A \subset P_{\text {in }}$ and $B \subset P_{\text {out }}$

## Dealing with $P_{\text {in }}, P_{\text {out }}$ (sketch)


$\operatorname{diam}\left(P_{\text {in }} \cup P_{\text {out }}\right) \leq 2 r / \varepsilon$
$\ell:=\min _{p \in P_{\text {in }}, q \in P_{\text {out }}}\|p-q\| \geq r / n$
snap points to a grid $G_{\alpha}$ with $\alpha=\varepsilon \ell / 10$
Use WSPD algorithm for bounded spread to compute WSPs with $A \subset P_{\text {in }}$ and $B \subset P_{\text {out }}$

- grid size: $O\left(n / \varepsilon^{2}\right)$


## Dealing with $P_{\text {in }}, P_{\text {out }}$ (sketch)


$\operatorname{diam}\left(P_{\text {in }} \cup P_{\text {out }}\right) \leq 2 r / \varepsilon$
$\ell:=\min _{p \in P_{\text {in }}, q \in P_{\text {out }}}\|p-q\| \geq r / n$
snap points to a grid $G_{\alpha}$ with $\alpha=\varepsilon \ell / 10$
Use WSPD algorithm for bounded spread to compute WSPs with $A \subset P_{\text {in }}$ and $B \subset P_{\text {out }}$

- grid size: $O\left(n / \varepsilon^{2}\right)$
- levels in quadtree: $O\left(\log \left(n / \varepsilon^{2}\right)\right)$
$\rightarrow$ \# pairs $=O(n \log n) \quad$ (low weight)


## Dealing with $P_{\text {in }}, P_{\text {out }}$ (sketch)


$\operatorname{diam}\left(P_{\text {in }} \cup P_{\text {out }}\right) \leq 2 r / \varepsilon$
$\ell:=\min _{p \in P_{\text {in }}, q \in P_{\text {out }}}\|p-q\| \geq r / n$
snap points to a grid $G_{\alpha}$ with $\alpha=\varepsilon \ell / 10$
Use WSPD algorithm for bounded spread to compute WSPs with $A \subset P_{\text {in }}$ and $B \subset P_{\text {out }}$

- grid size: $O\left(n / \varepsilon^{2}\right)$
- levels in quadtree: $O\left(\log \left(n / \varepsilon^{2}\right)\right)$
$\rightarrow$ \# pairs $=O(n \log n) \quad$ (low weight)
- snapping: since $\ell \geq r / n$ distances between $p \in P_{\text {in }}$ and $q \in P_{\text {out }}$ approximately stay the same.


## Summary

( $1 / \varepsilon$ )-Semi-separated pair decomposition (SSPD)

$$
\min \left(r_{A}, r_{B}\right) \leq \varepsilon d(A, B)
$$

## Summary

$(1 / \varepsilon)$-Semi-separated pair decomposition (SSPD)

$$
\min \left(r_{A}, r_{B}\right) \leq \varepsilon d(A, B)
$$

Ring separator tree: $n$-semi-separated pair decomposition

$$
\text { enclose constant fraction } A \text { of } P \text { by ball } b(c, r) \text { s.t. } \operatorname{dist}(A, P \backslash A) \geq r / n
$$

## Summary

( $1 / \varepsilon$ )-Semi-separated pair decomposition (SSPD)

$$
\min \left(r_{A}, r_{B}\right) \leq \varepsilon d(A, B)
$$

Ring separator tree: $n$-semi-separated pair decomposition enclose constant fraction $A$ of $P$ by ball $b(c, r)$ s.t. $\operatorname{dist}(A, P \backslash A) \geq r / n$

Ring separator tree: $O(n)$-ANN
data structure of size $O(n)$ computed in $O(n \log n)$ time, which gives $n$-ANN in $O(\log n)$ time

## Summary

( $1 / \varepsilon$ )-Semi-separated pair decomposition (SSPD)

$$
\min \left(r_{A}, r_{B}\right) \leq \varepsilon d(A, B)
$$

Ring separator tree: $n$-semi-separated pair decomposition enclose constant fraction $A$ of $P$ by ball $b(c, r)$ s.t. $\operatorname{dist}(A, P \backslash A) \geq r / n$

Ring separator tree: $O(n)$-ANN
data structure of size $O(n)$ computed in $O(n \log n)$ time, which gives $n$-ANN in $O(\log n)$ time
( $1 / \varepsilon$ )-semi-separated pair decomposition $n$-ring separator + snap to grid + WSPD

