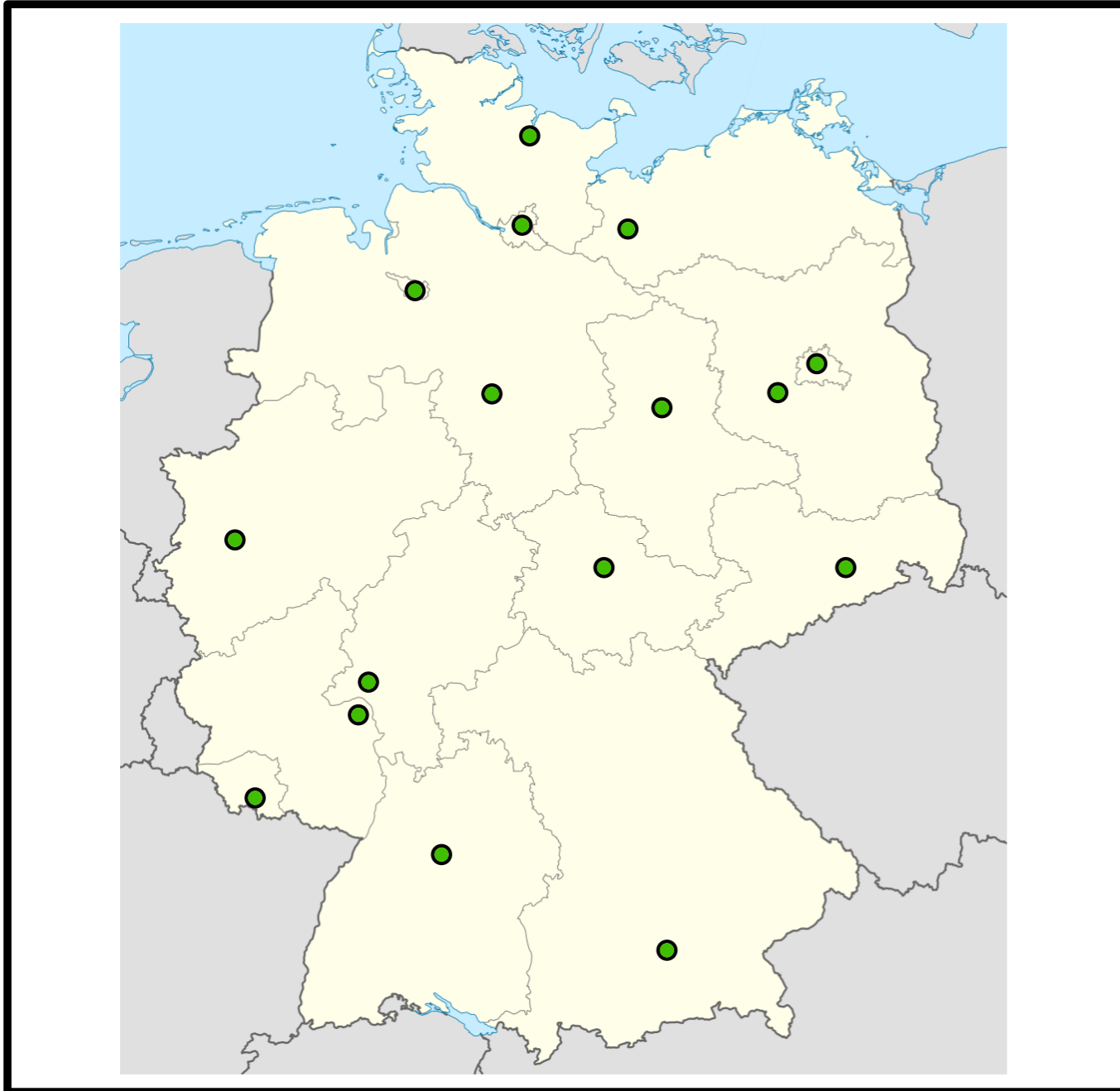


# Quadrees

Geometric Approximation Algorithms

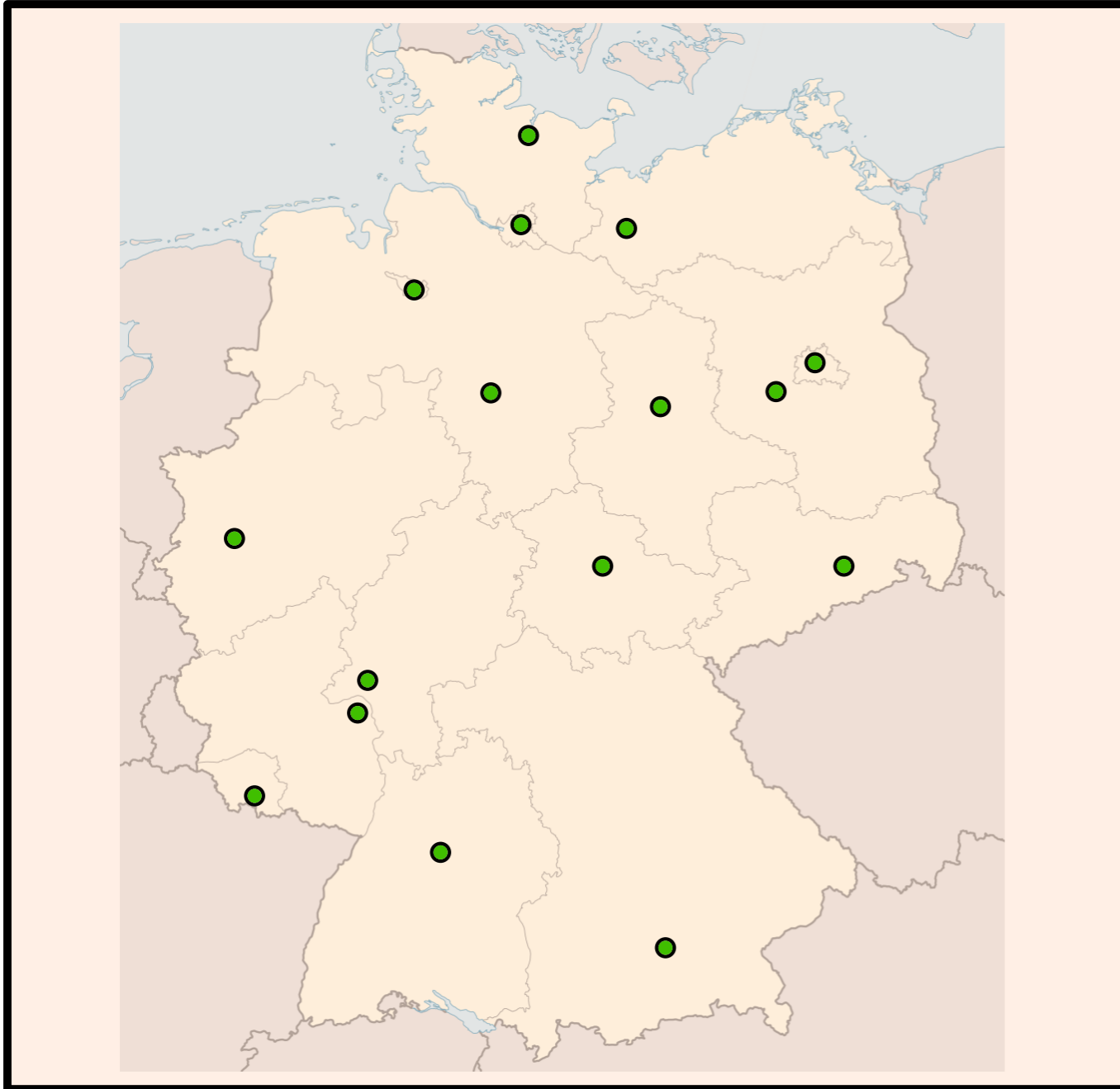
# Quadtrees: a simple point-location data structure



**Main idea:** Use a **tree structure** to be able to quickly find location of point

- nodes represent squares
- recursively subdivide squares into 4 until 1 point per square

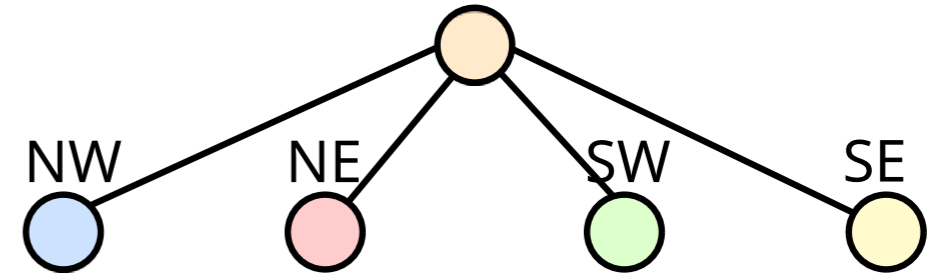
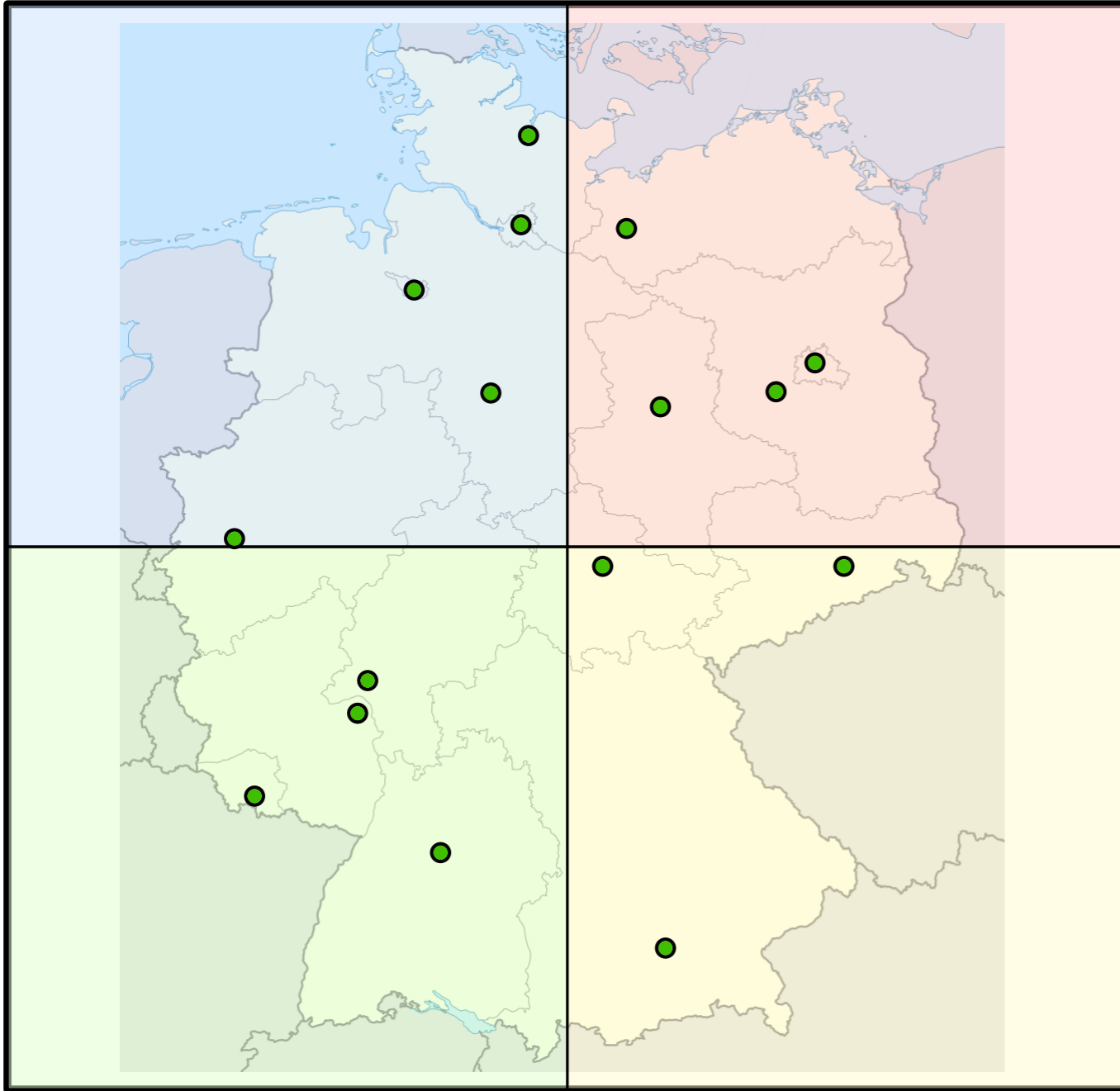
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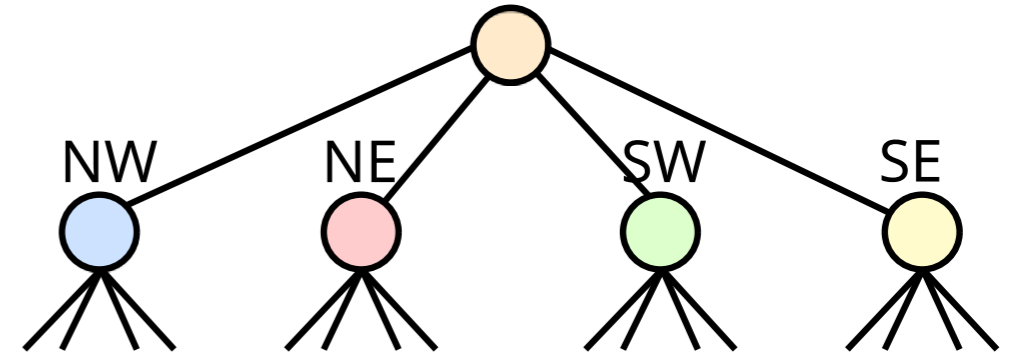
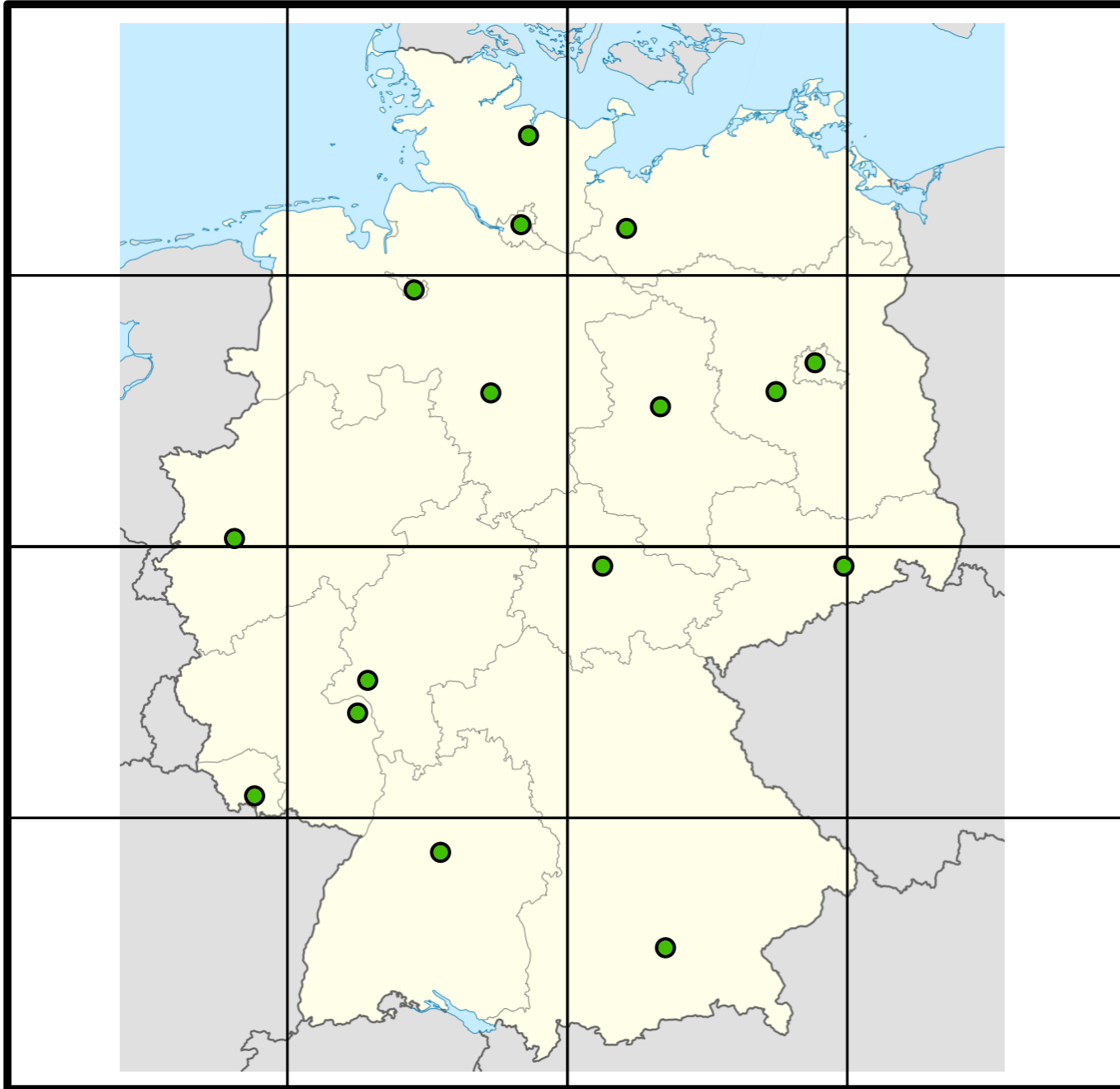
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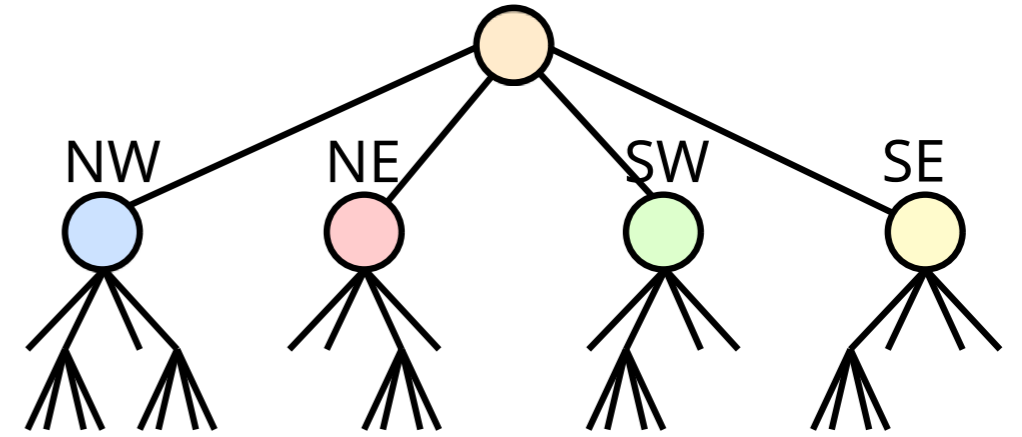
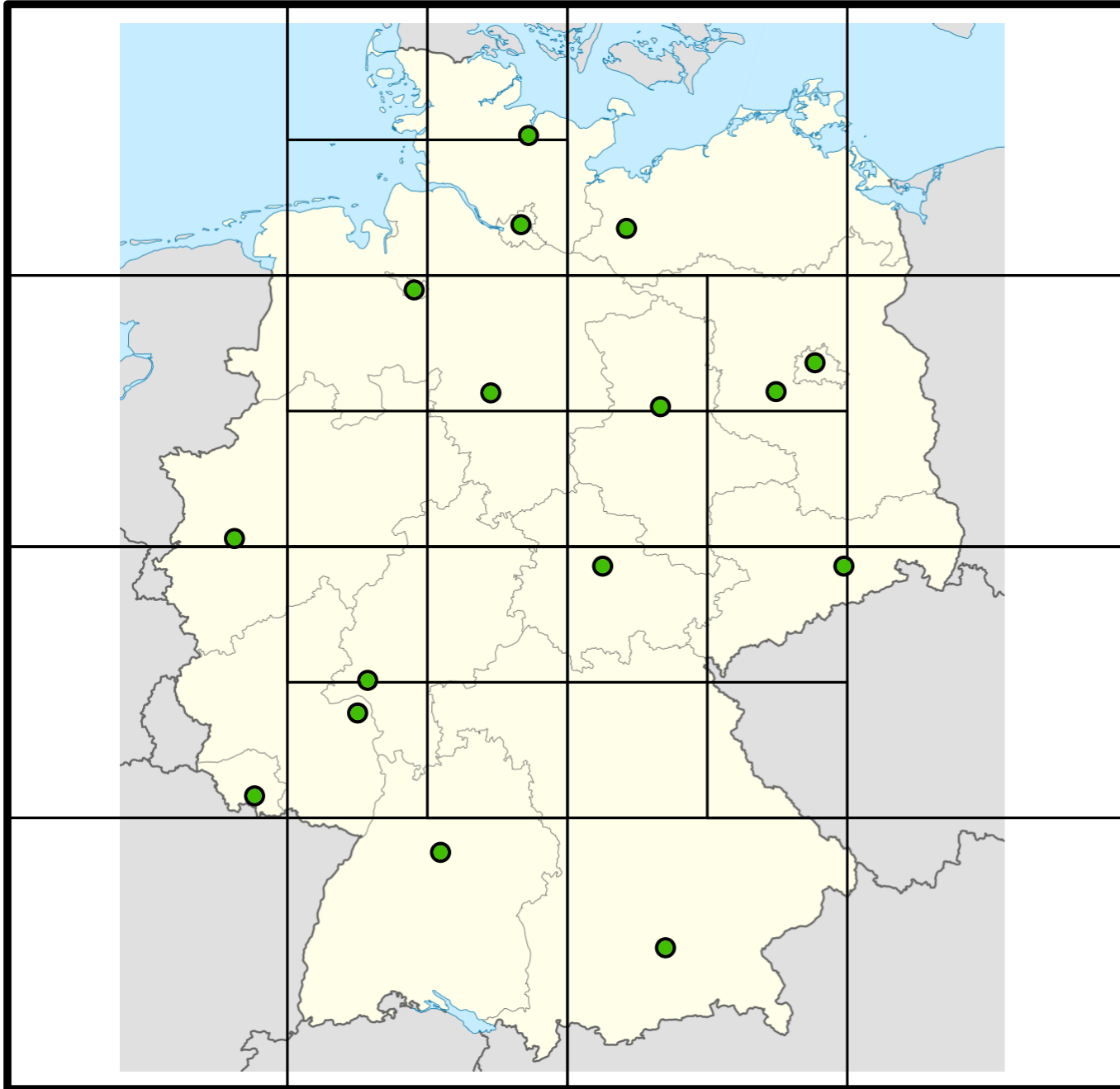
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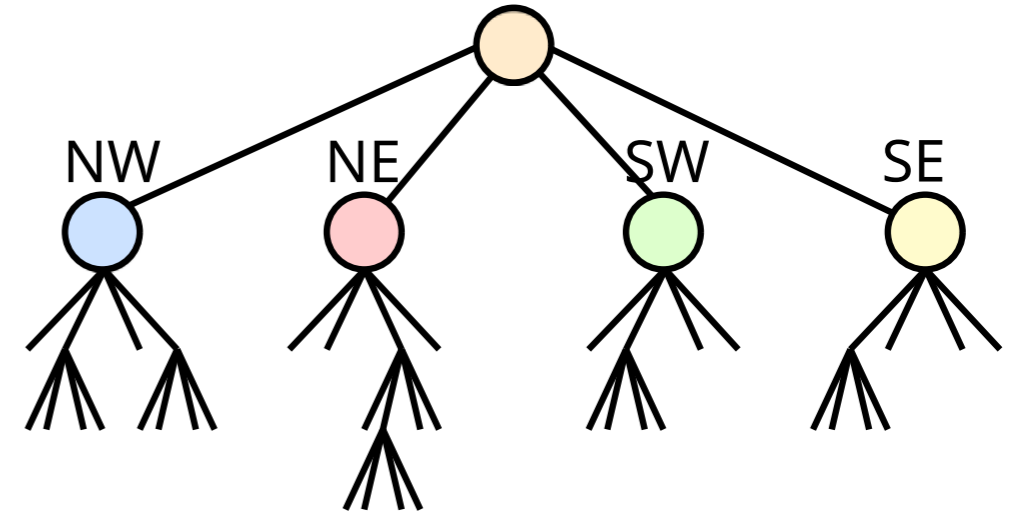
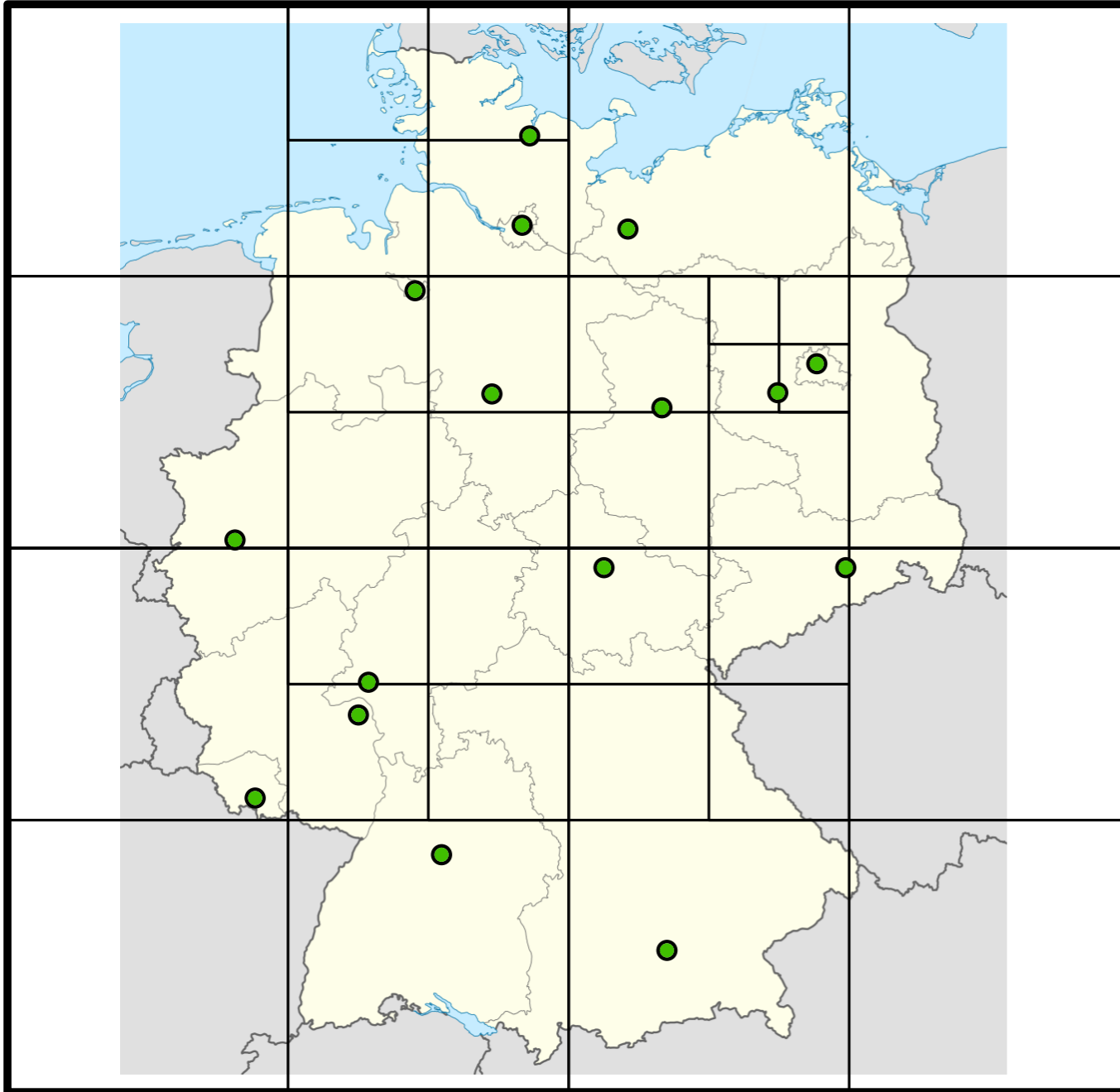
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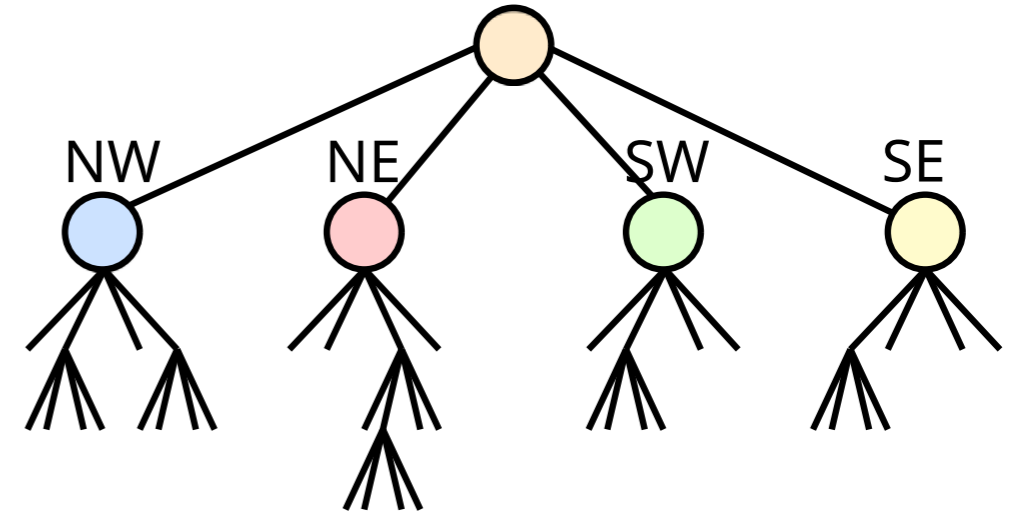
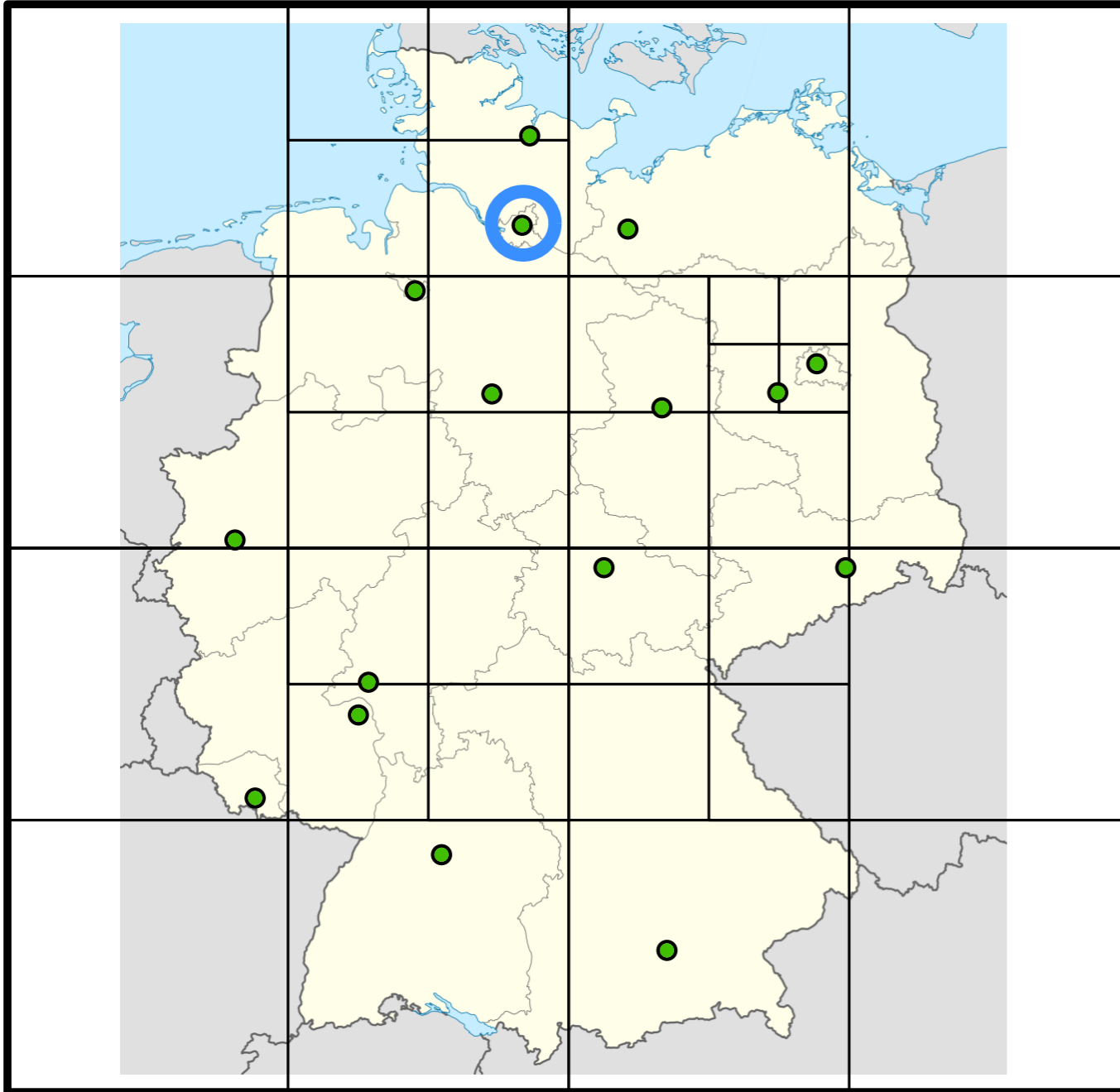
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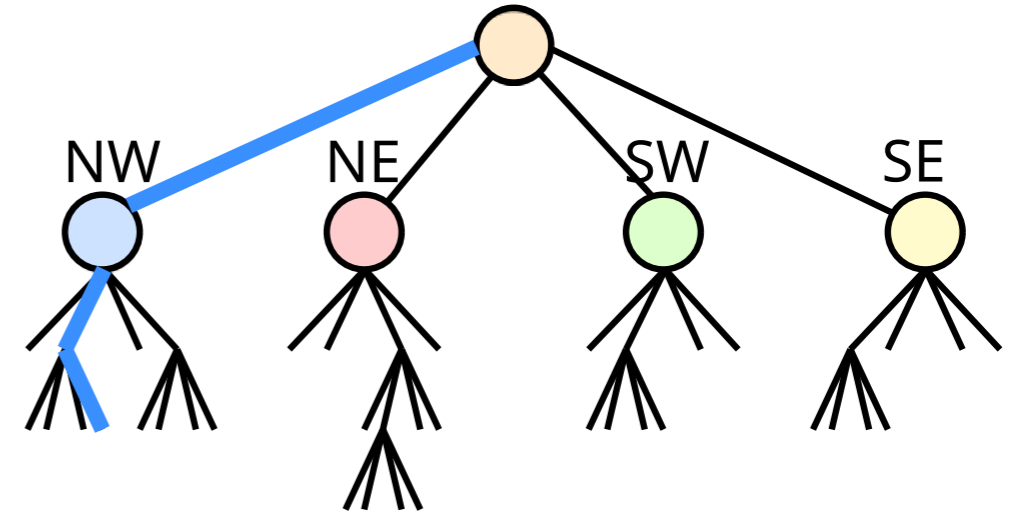
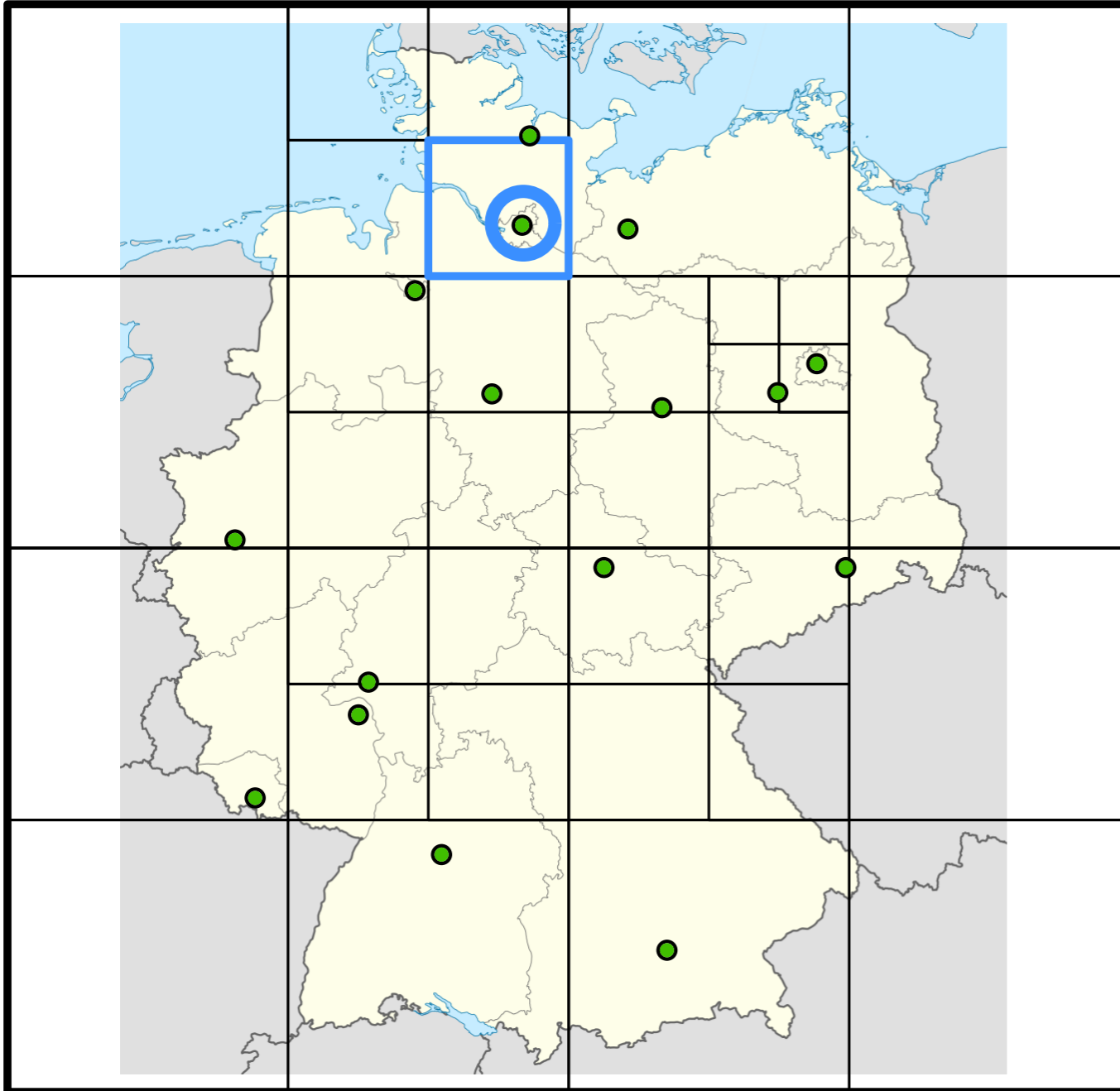


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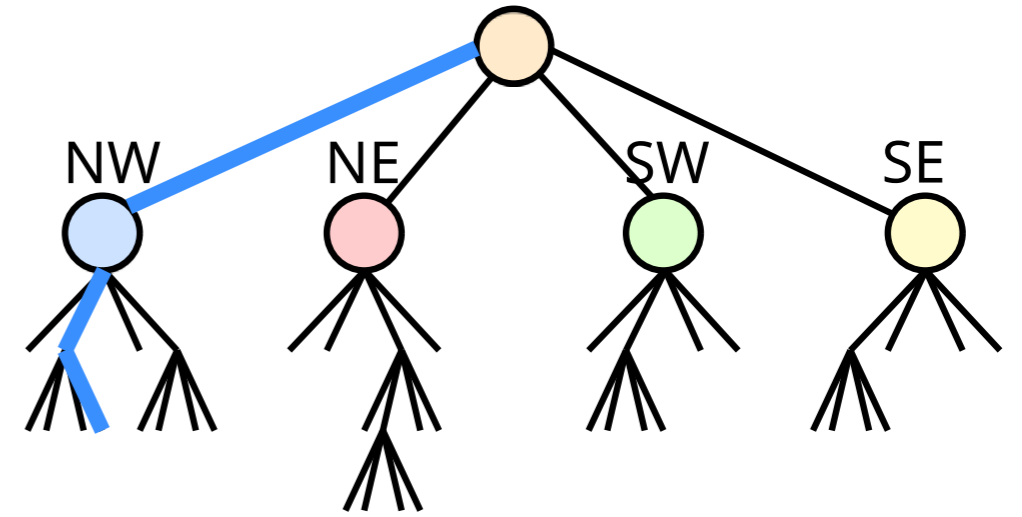
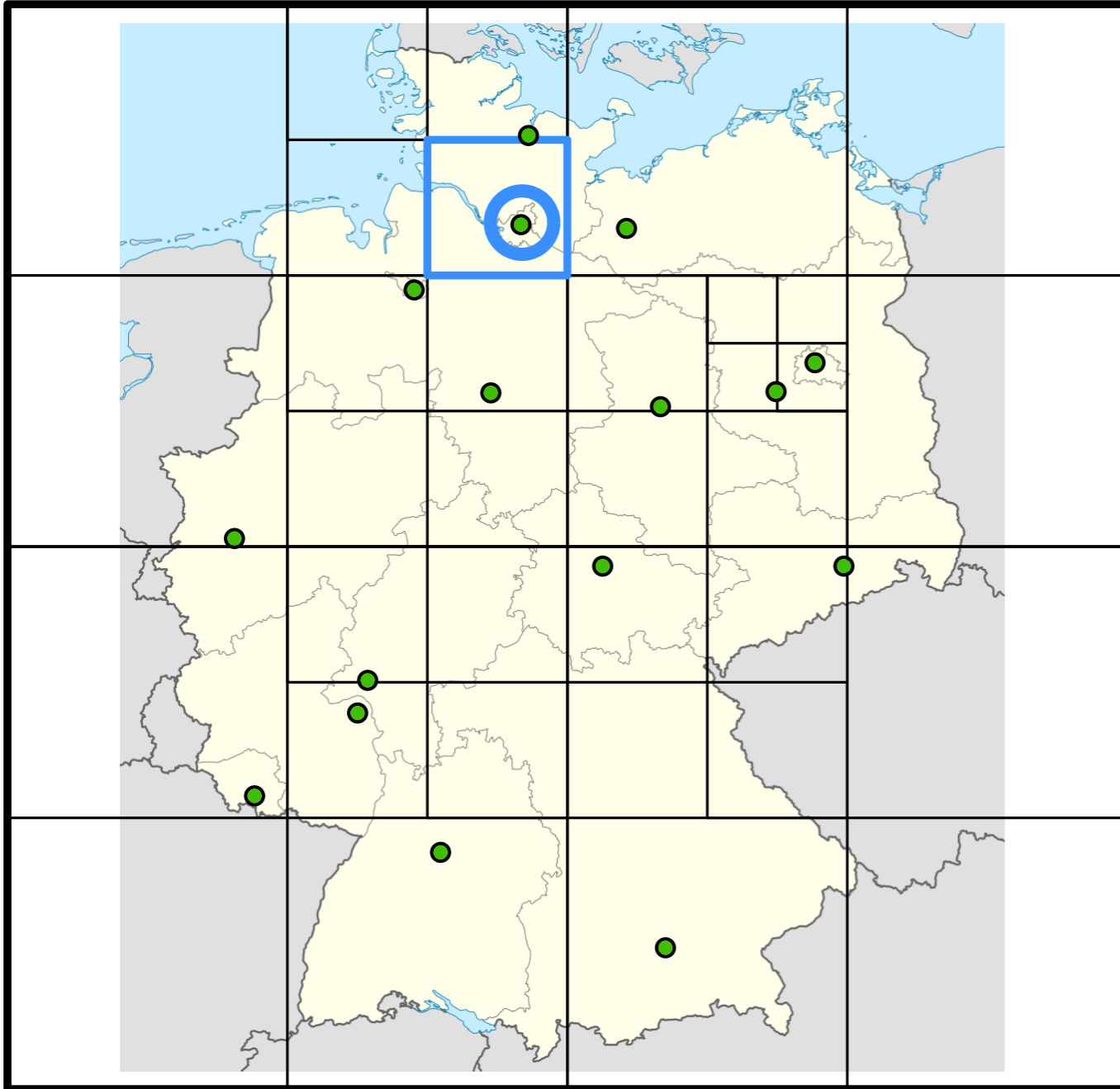
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# Quadtrees: a simple point-location data structure



Simple point location:  $O(d)$

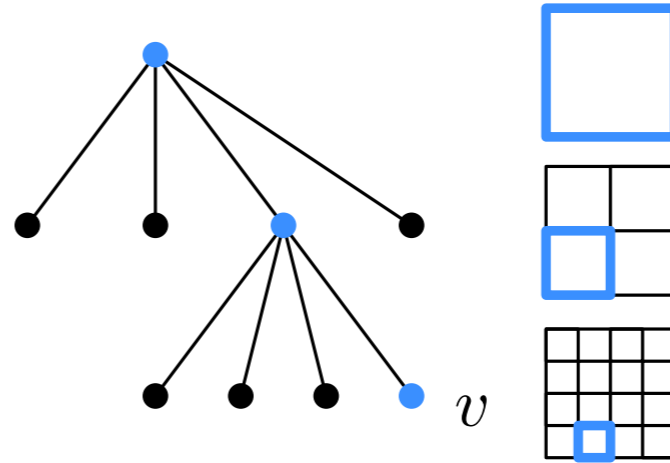
for  $n$  points and quadtree of depth  $d$

(+ check regions overlapping with leaf square)

# Quadtrees: multi-scale grids

node  $v$  at depth  $i$ :

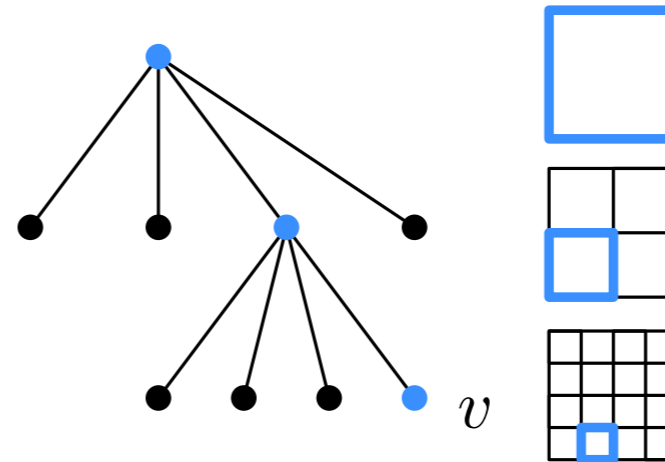
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- in grid  $G_{2^{-i}}$
- level  $\ell(v) = -i$
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with  $(x, y)$  a point in  $S_v$



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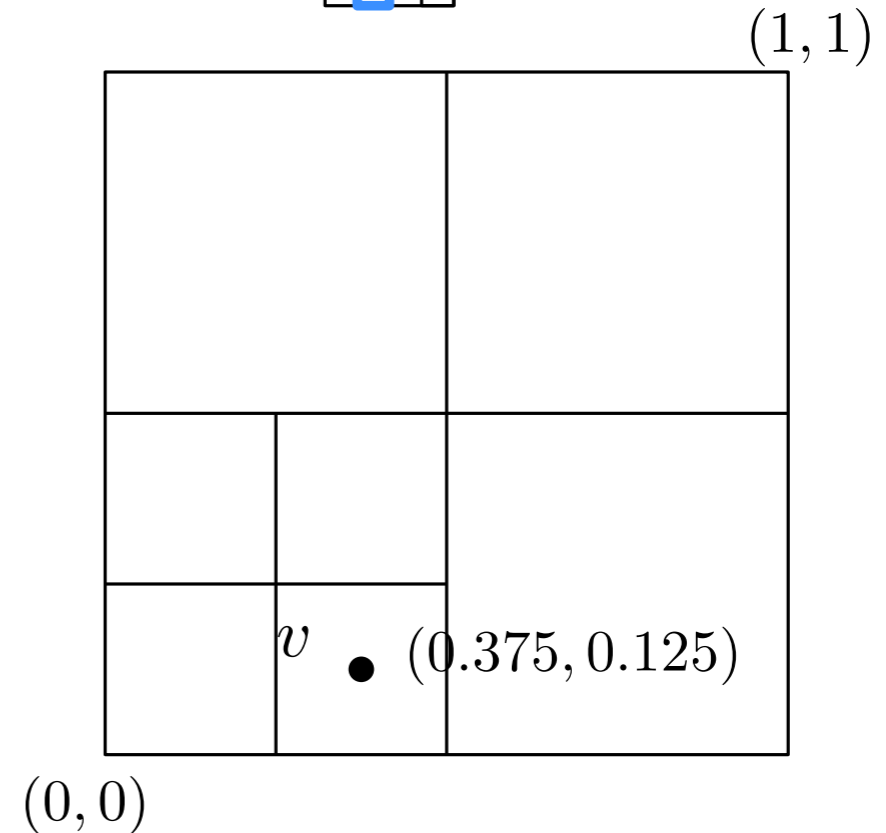
**Quiz** What is  $id(v)$  in this example?

A (-1,2,1)

B (-1,3,4)

C (-2,2,2)

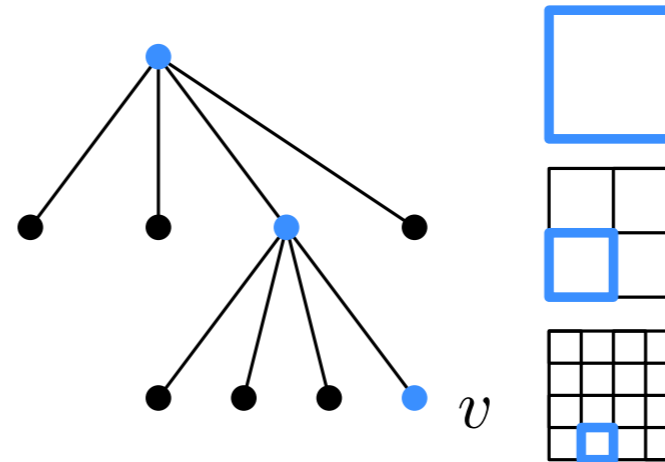
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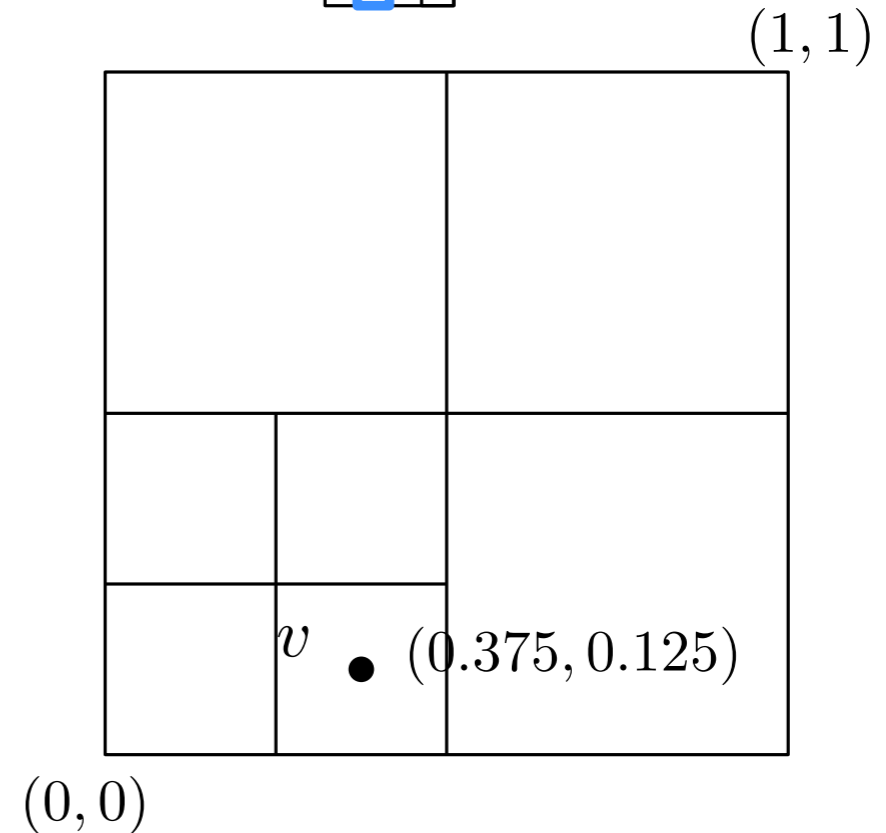
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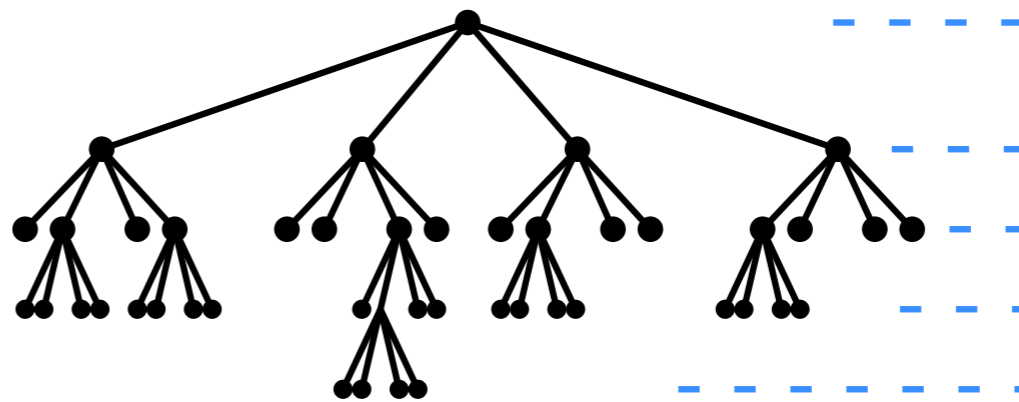
D (-2,1,0)



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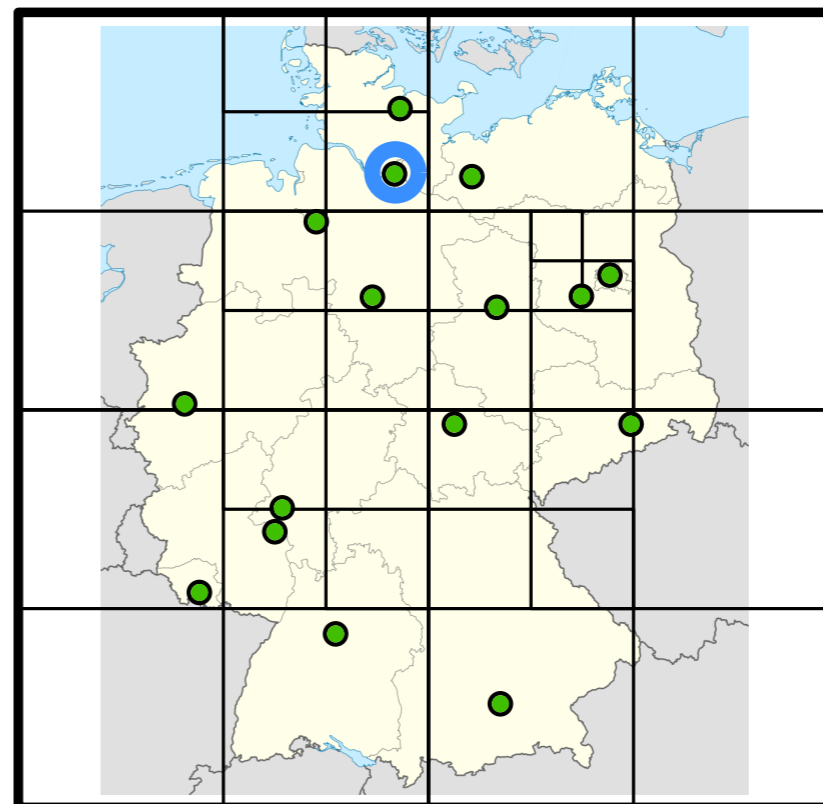
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Faster point location:

preprocessing: build hash table using  $id(v)$

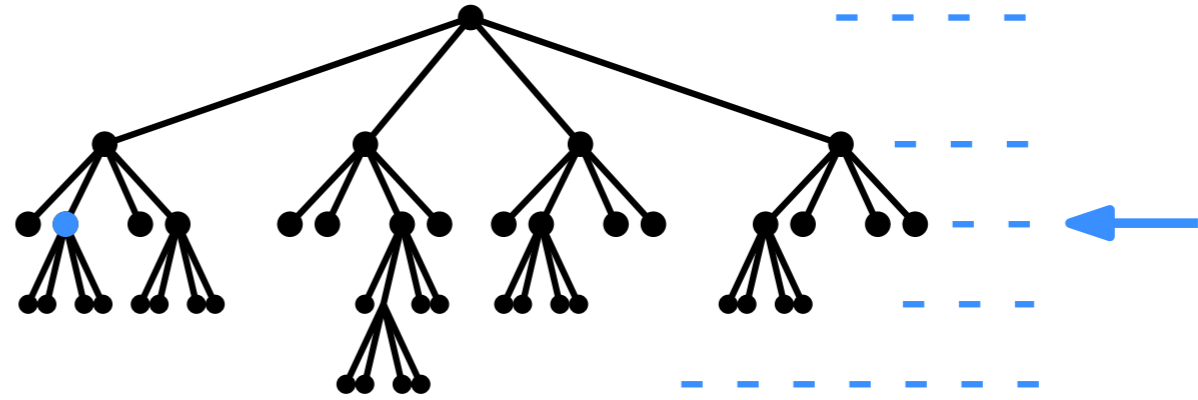
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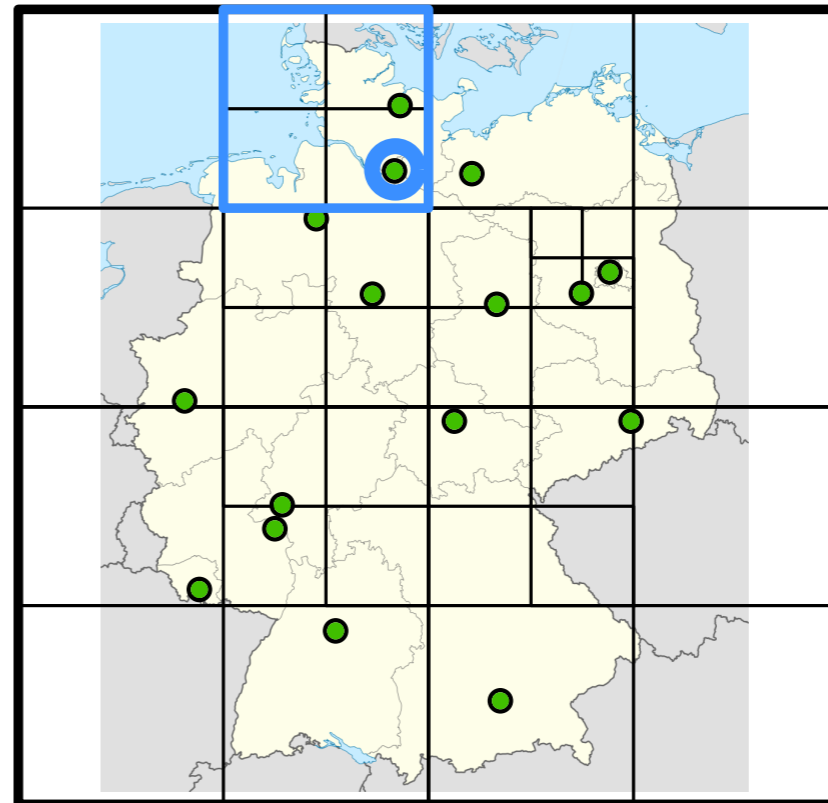


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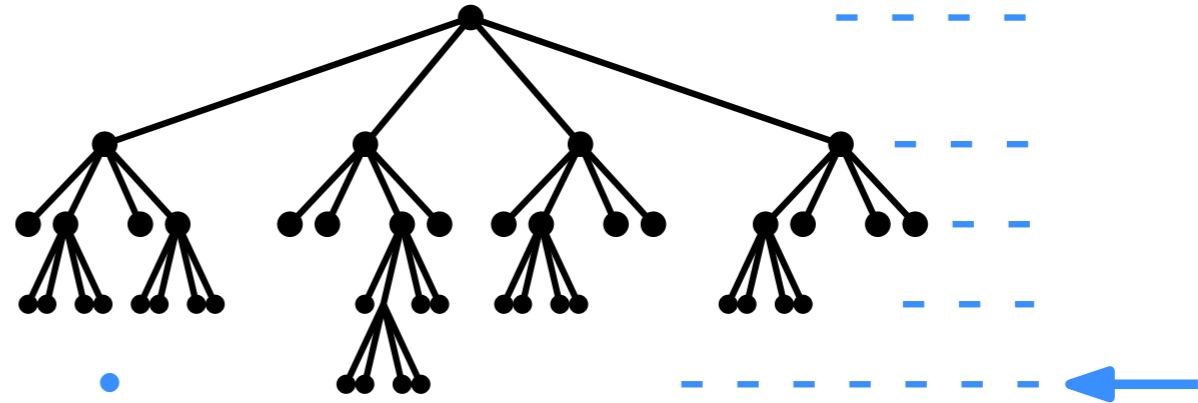
- if inner node: recurse in lower half



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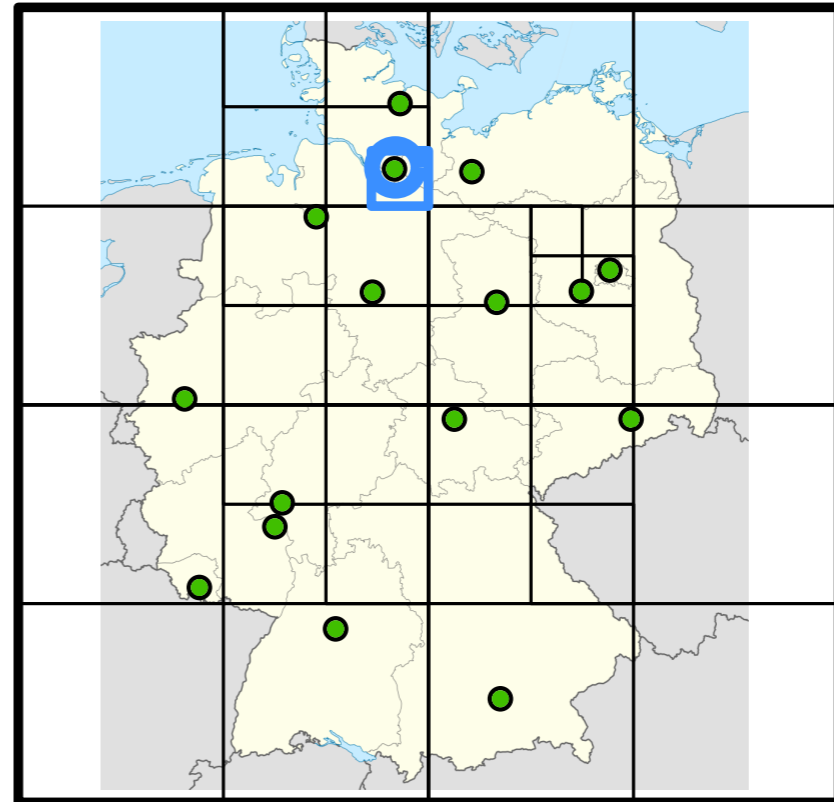


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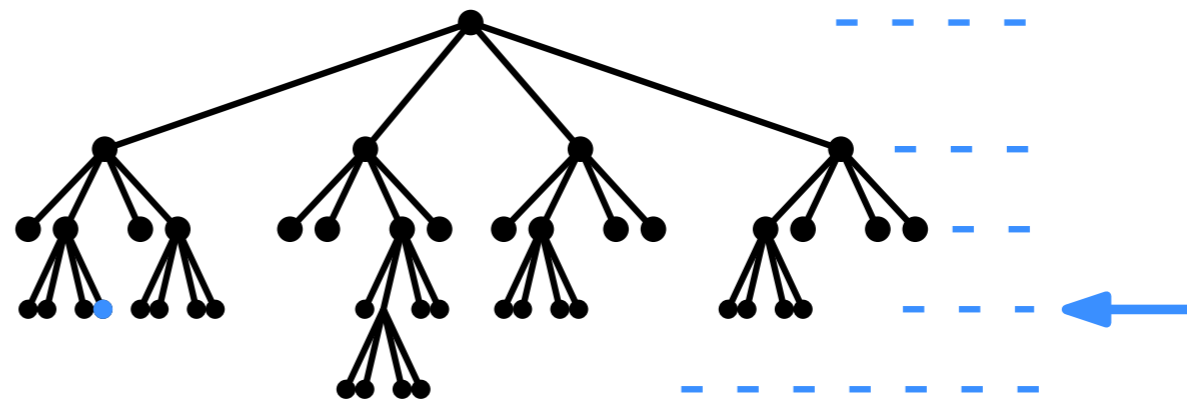




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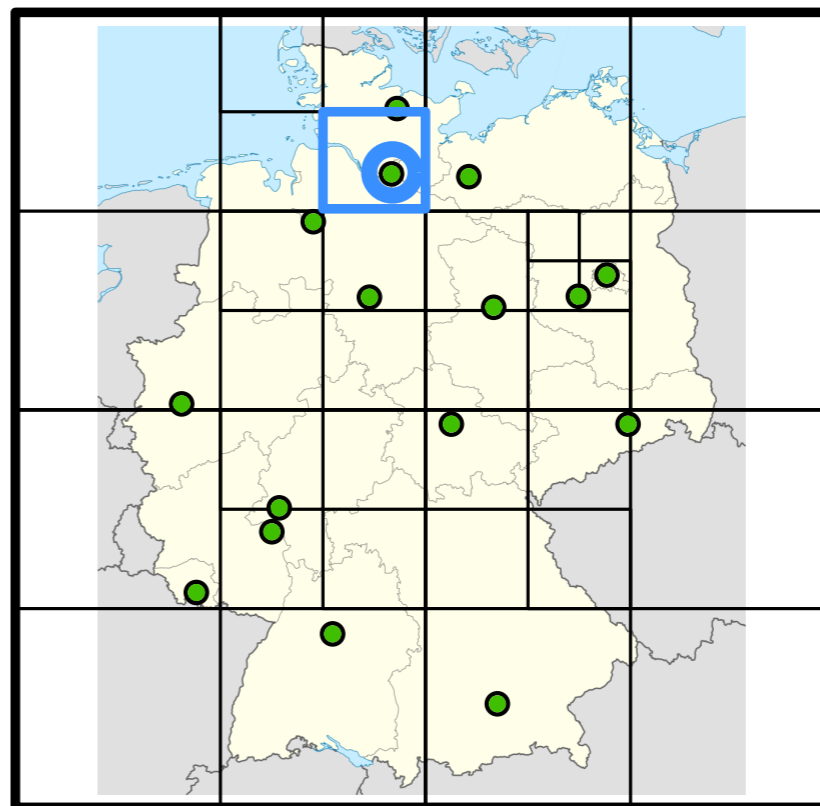


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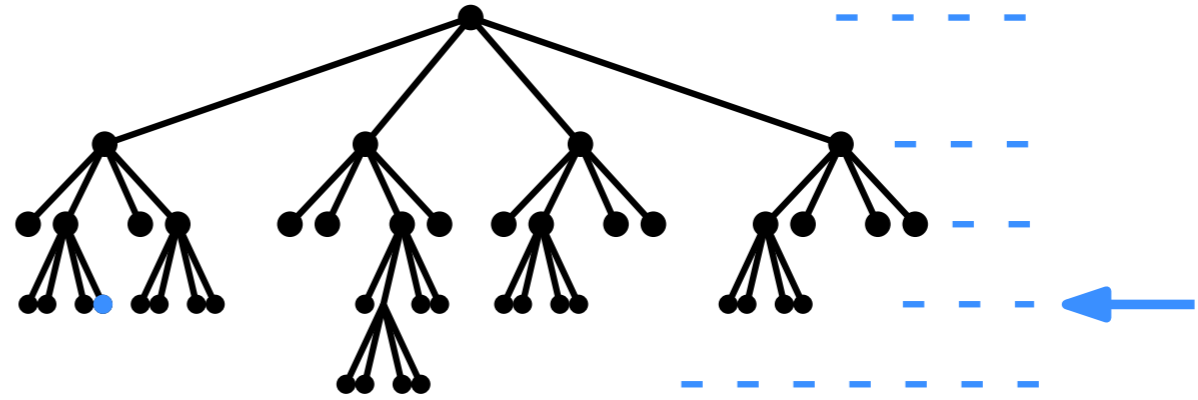
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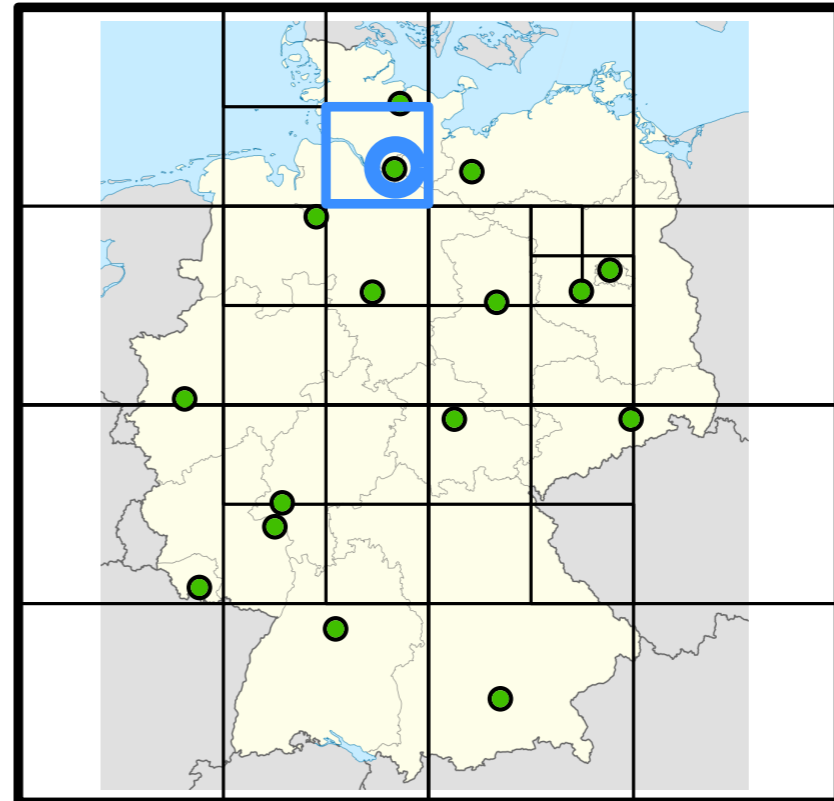
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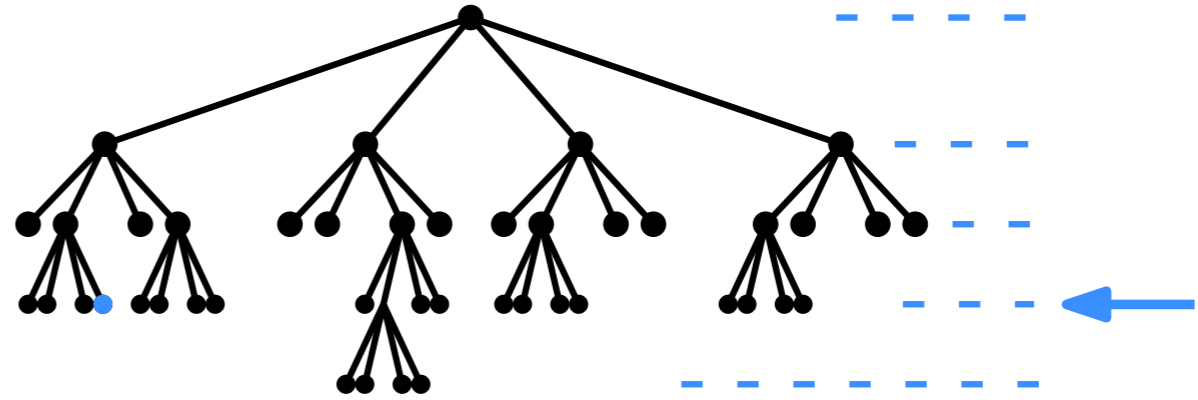
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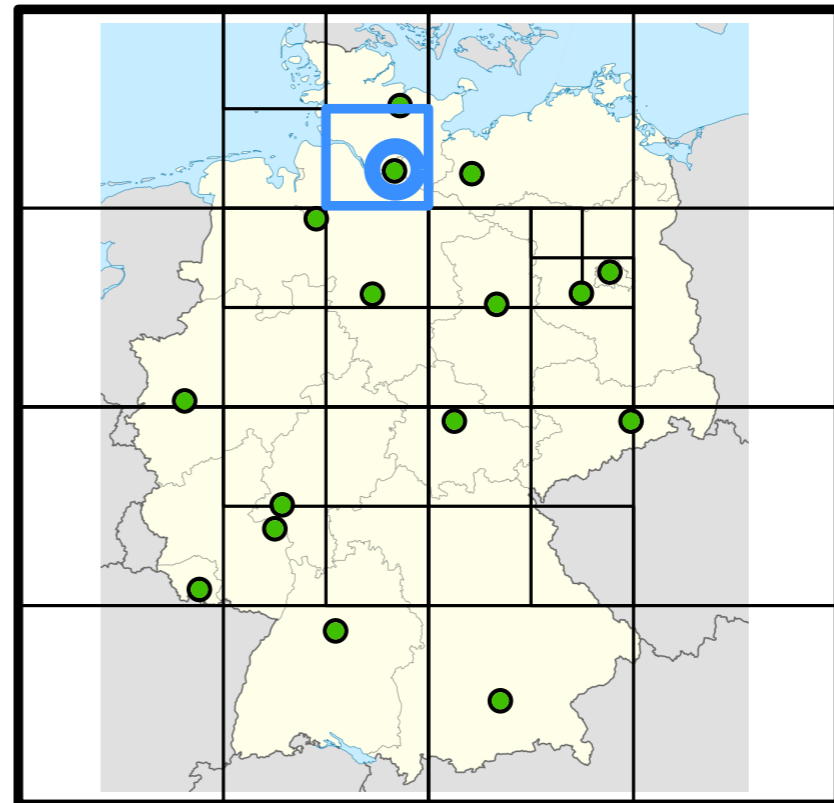
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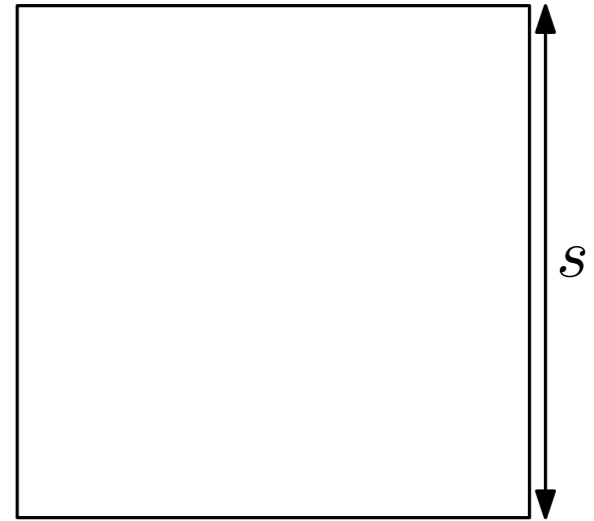


How large is  $d$ ? How large is the quadtree?



# Quadtree: depth and size

**Lemma:** Let  $c$  be the smallest distance between any two points in a point set  $P$ , and let  $s$  be the side length of the initial (biggest) square. Then the depth of a quadtree for  $P$  is at most  $\log(s/c) + 3/2$ .

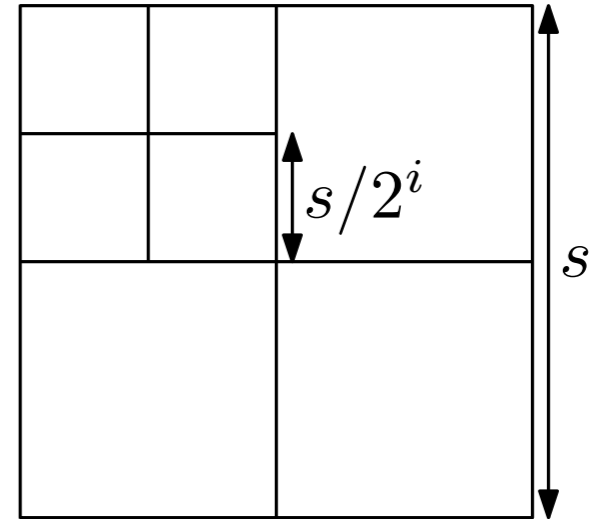


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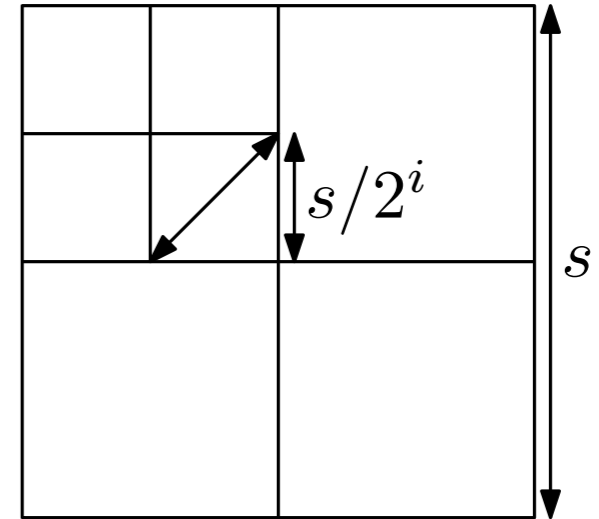


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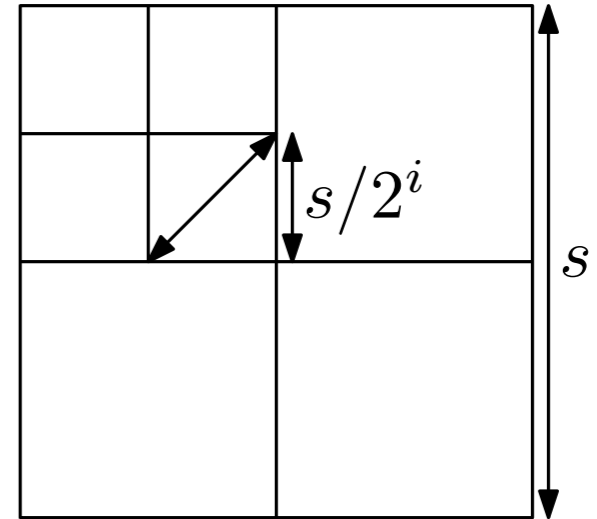
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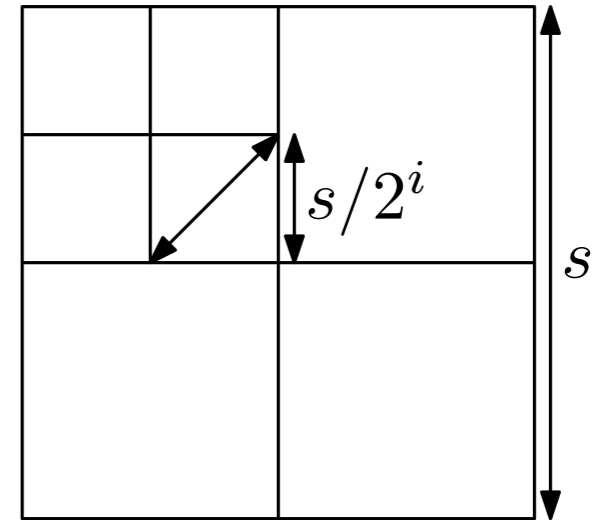
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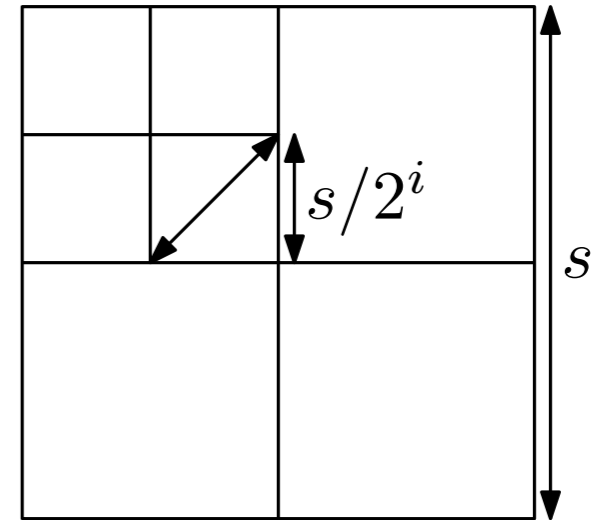
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$\Rightarrow$  depth of quadtree  $\leq \log(s/c) + 1/2 + 1$ , since nodes with  $\leq 1$  points have no children



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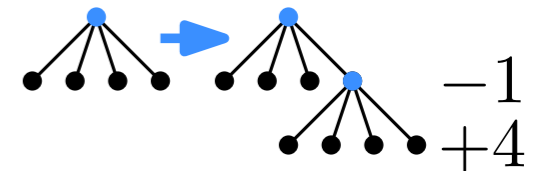
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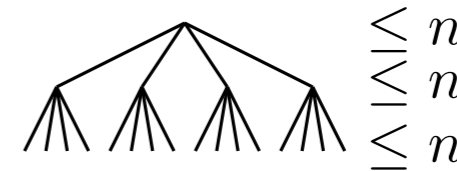
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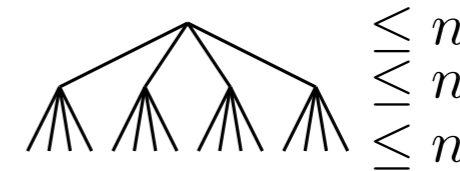
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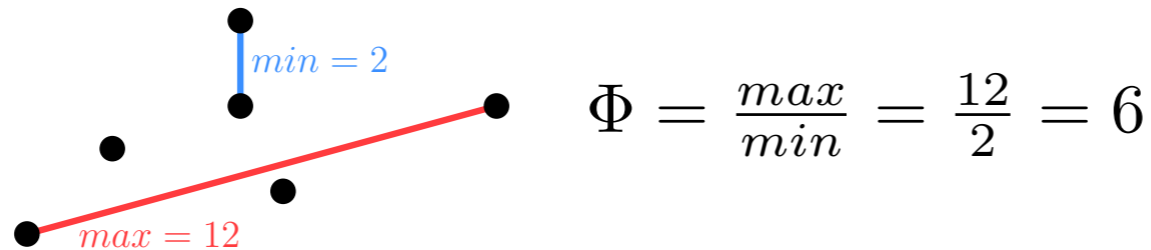
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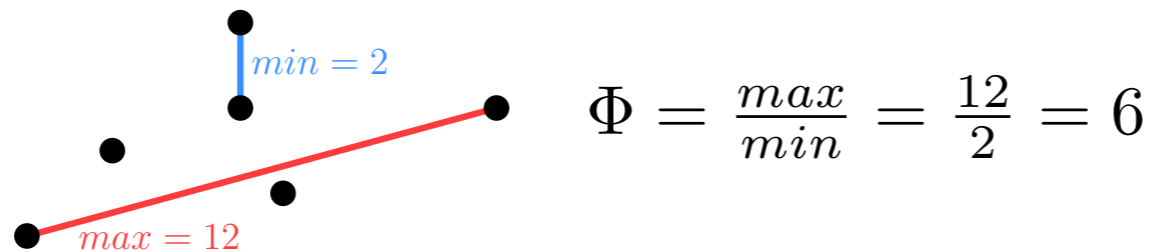


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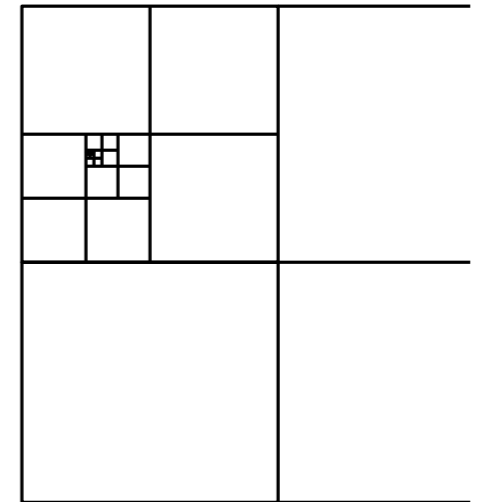
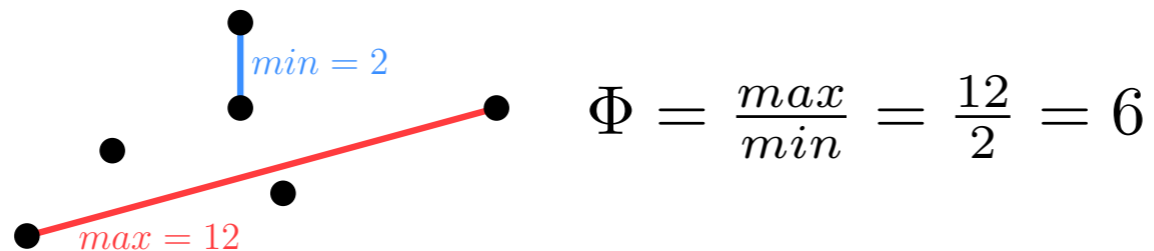
**Observation:** The depth of a quadtree is in  $O(\log(\Phi(P)))$  and the size in  $O(n \log \Phi(P))$ .

# Quadtree: depth and size

**Lemma:** Let  $c$  be the smallest distance between any two points in a point set  $P$ , and let  $s$  be the side length of the initial (biggest) square. Then the depth of a quadtree for  $P$  is at most  $\log(s/c) + 3/2$ .

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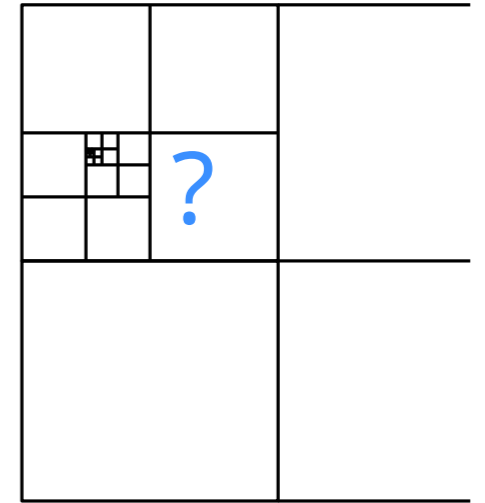


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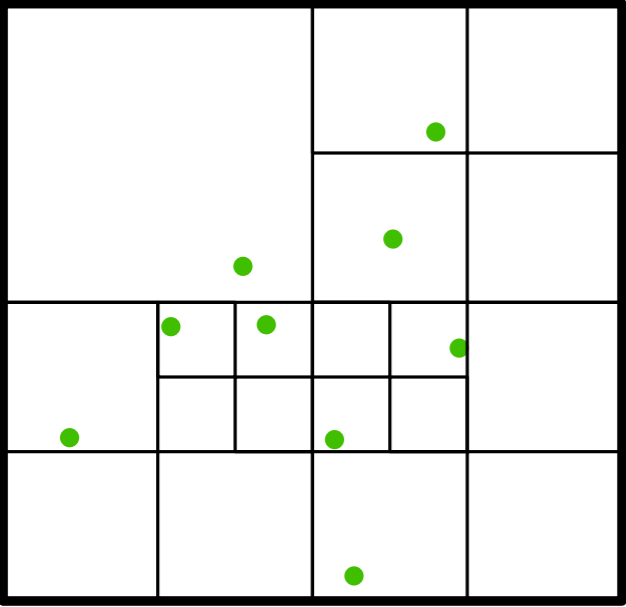
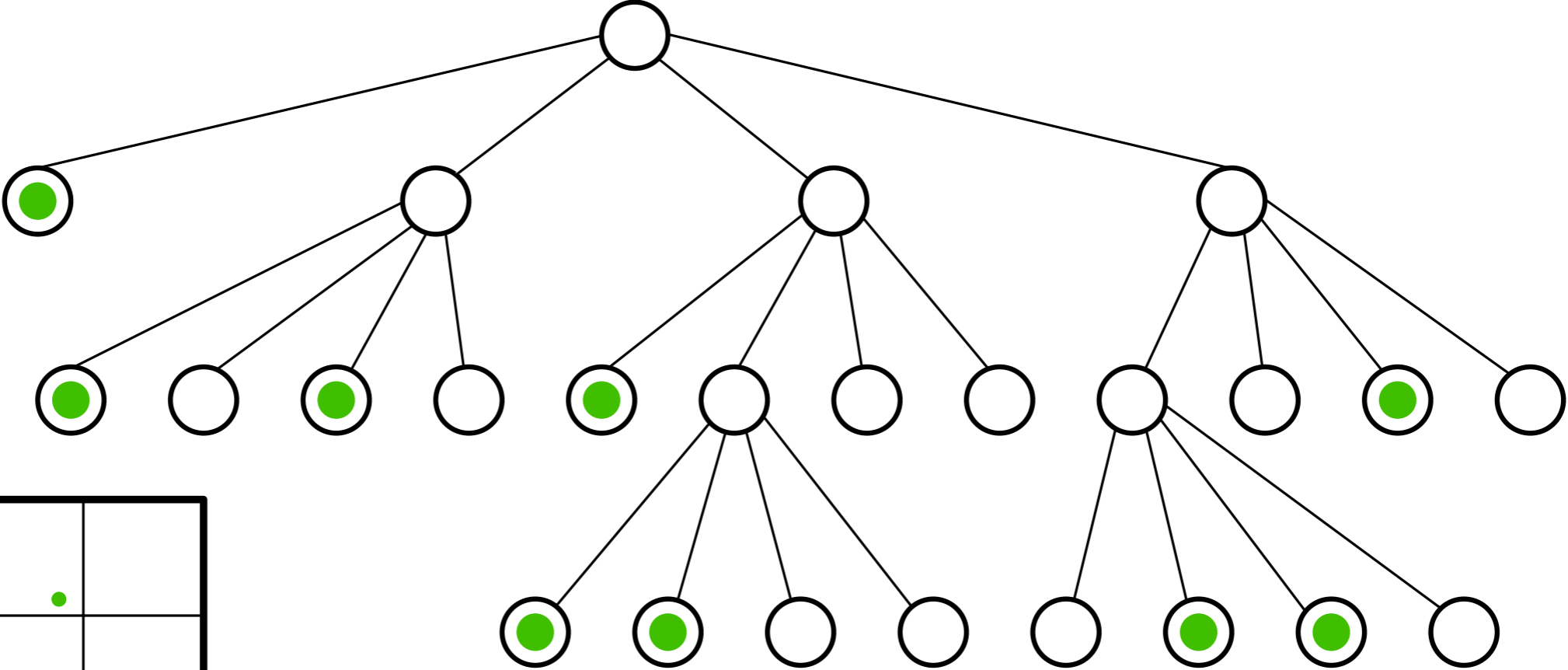
How can we handle the case when  $\Phi(P)$  is not bounded by a polynomial in  $n$ ? Can we get a linear-size data structure?



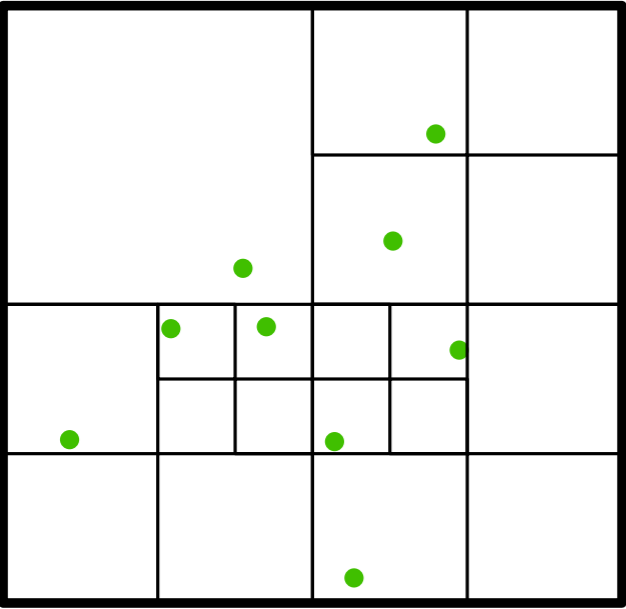
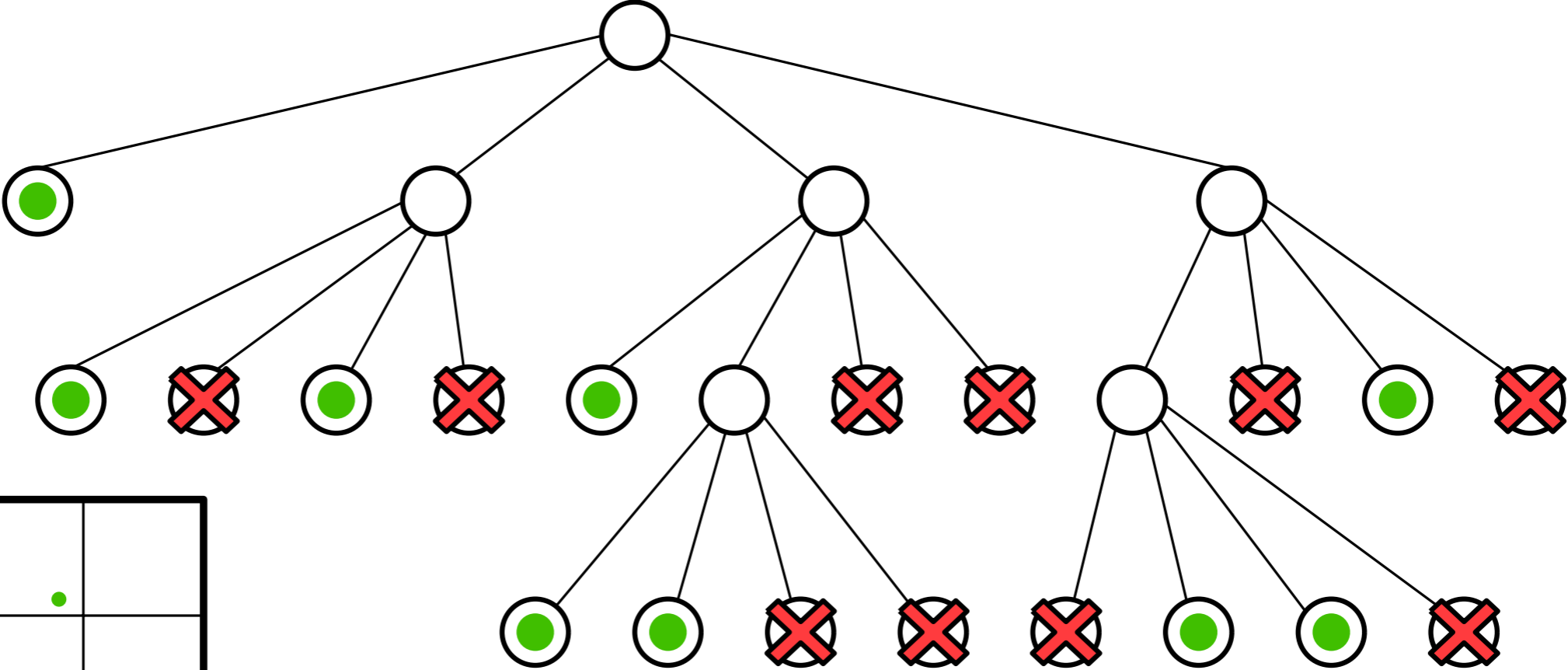
# Compressed Quadtrees



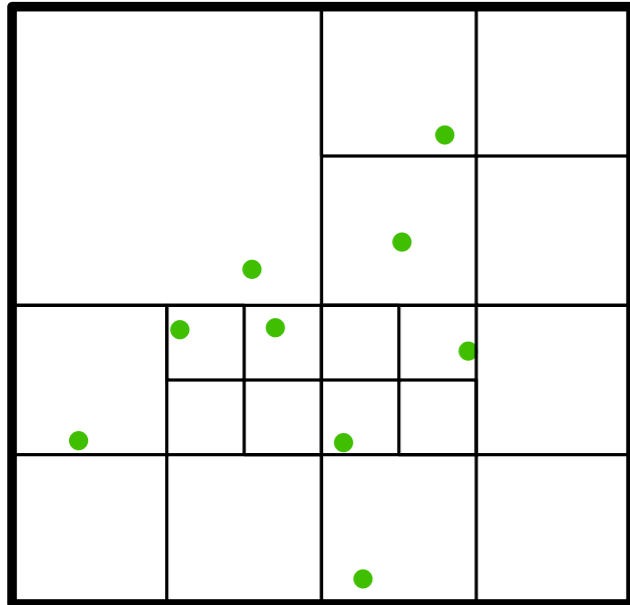
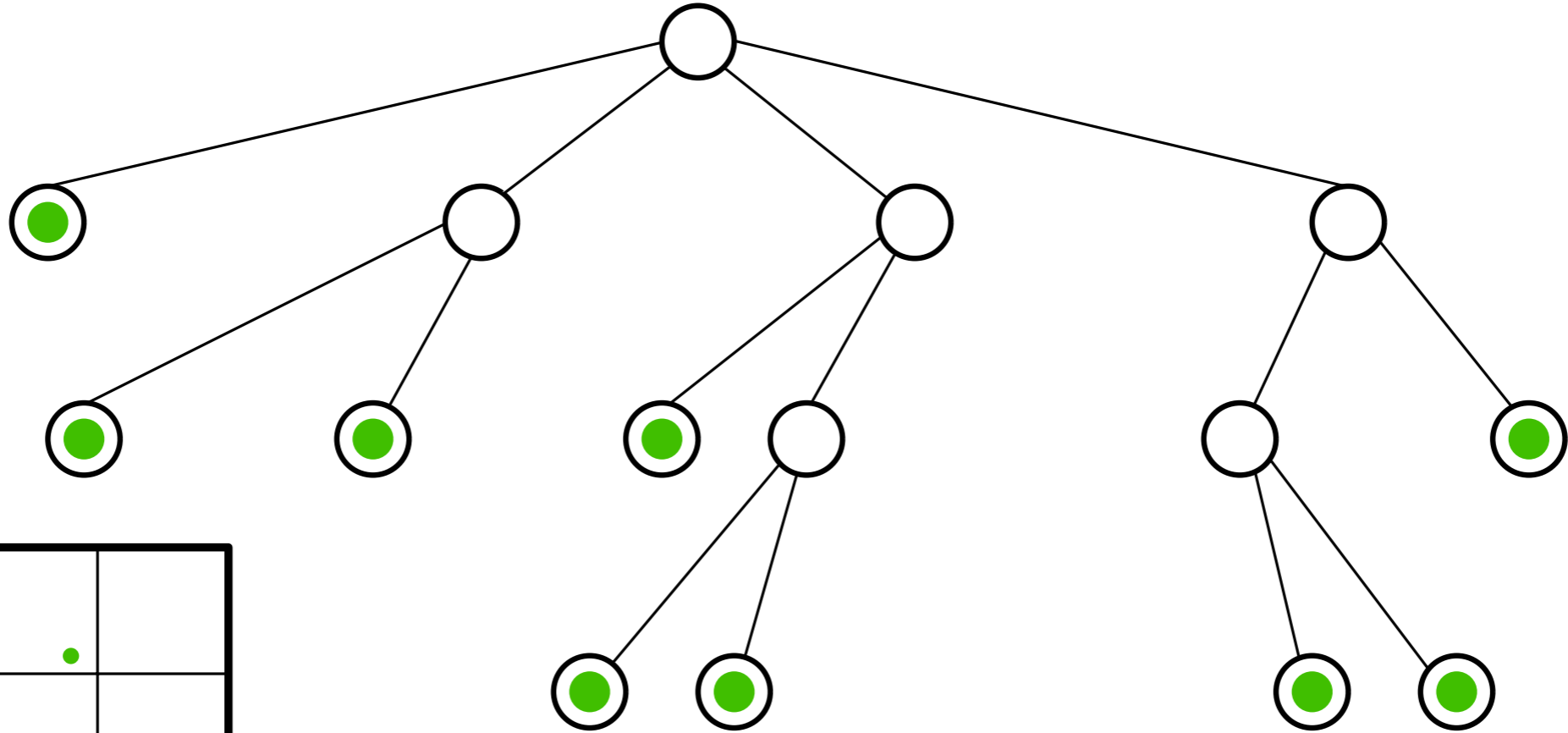
# Improving the size, step 0



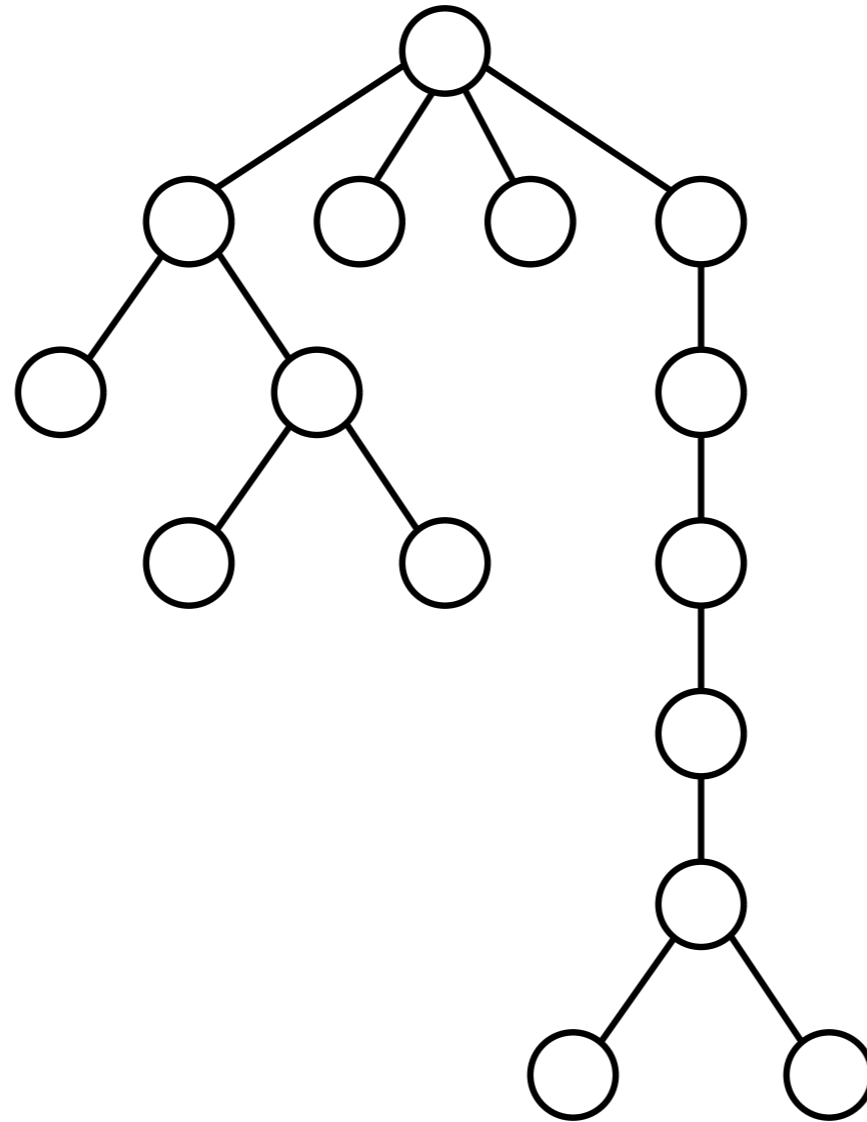
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# Compressed Quadtrees



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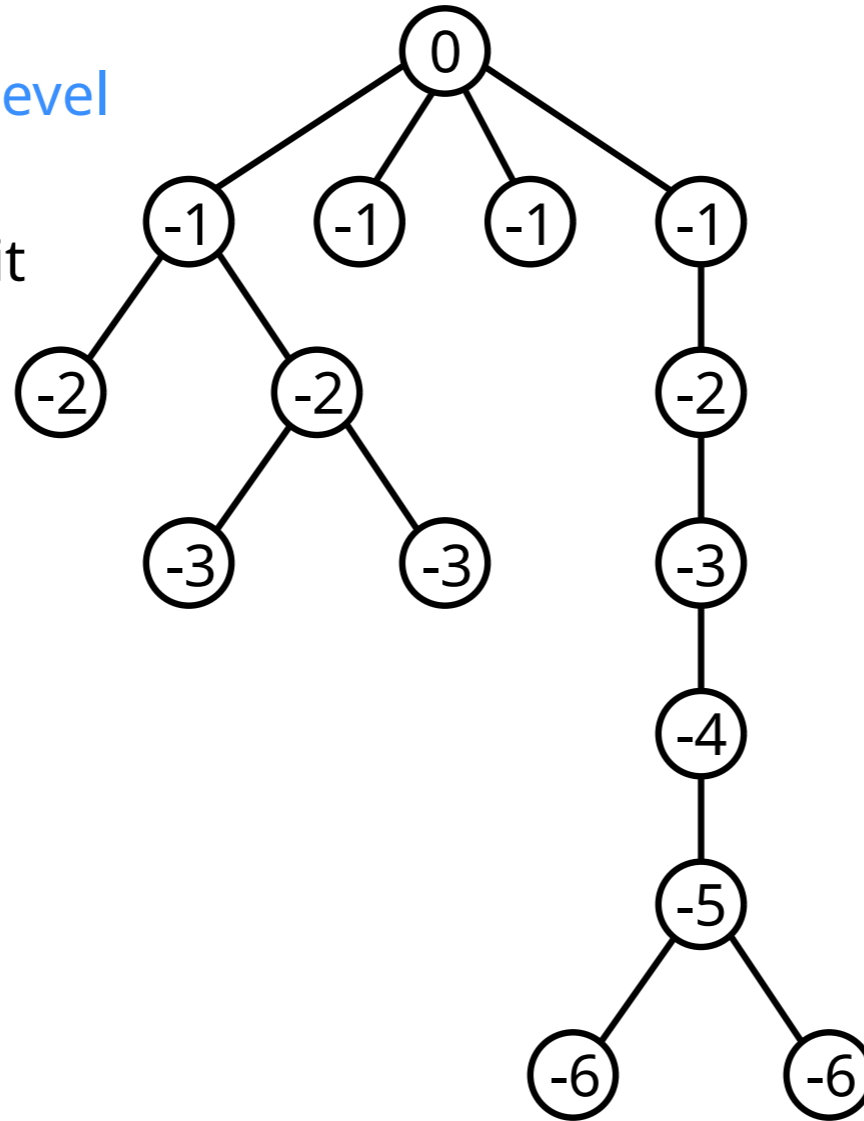
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Each node gets:

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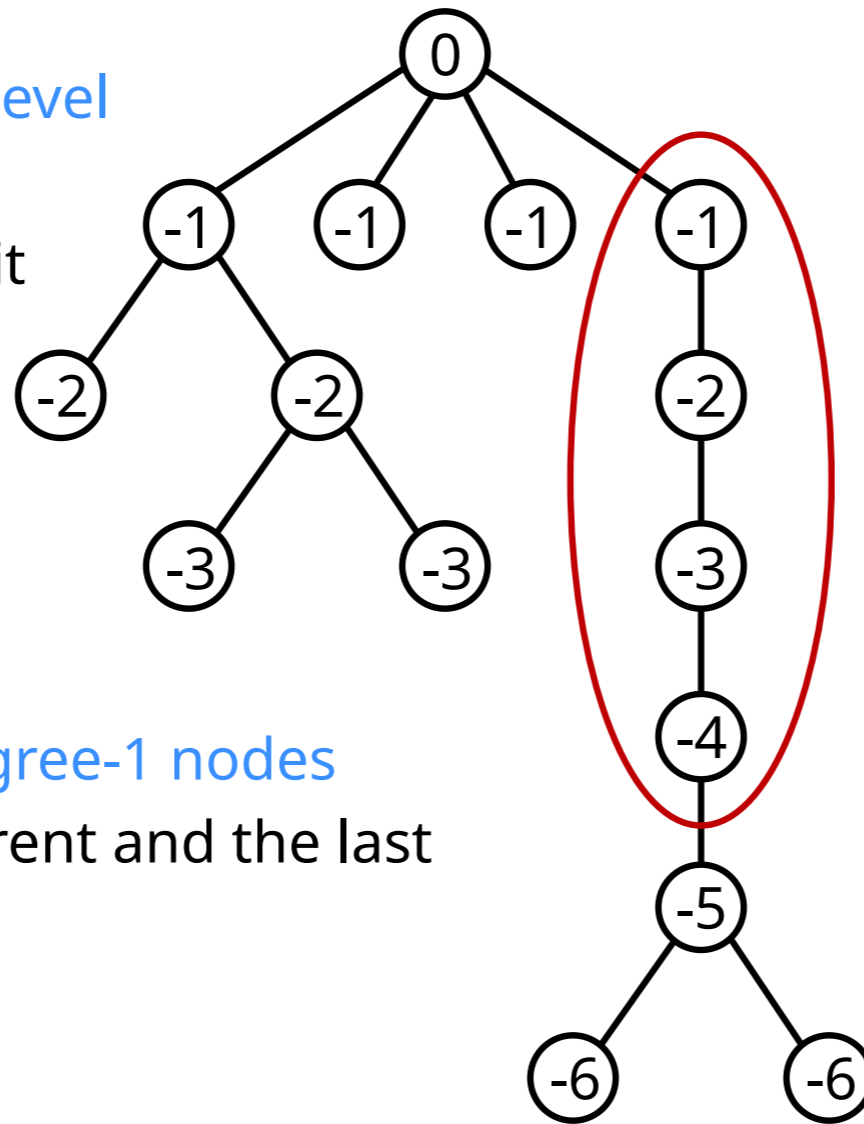
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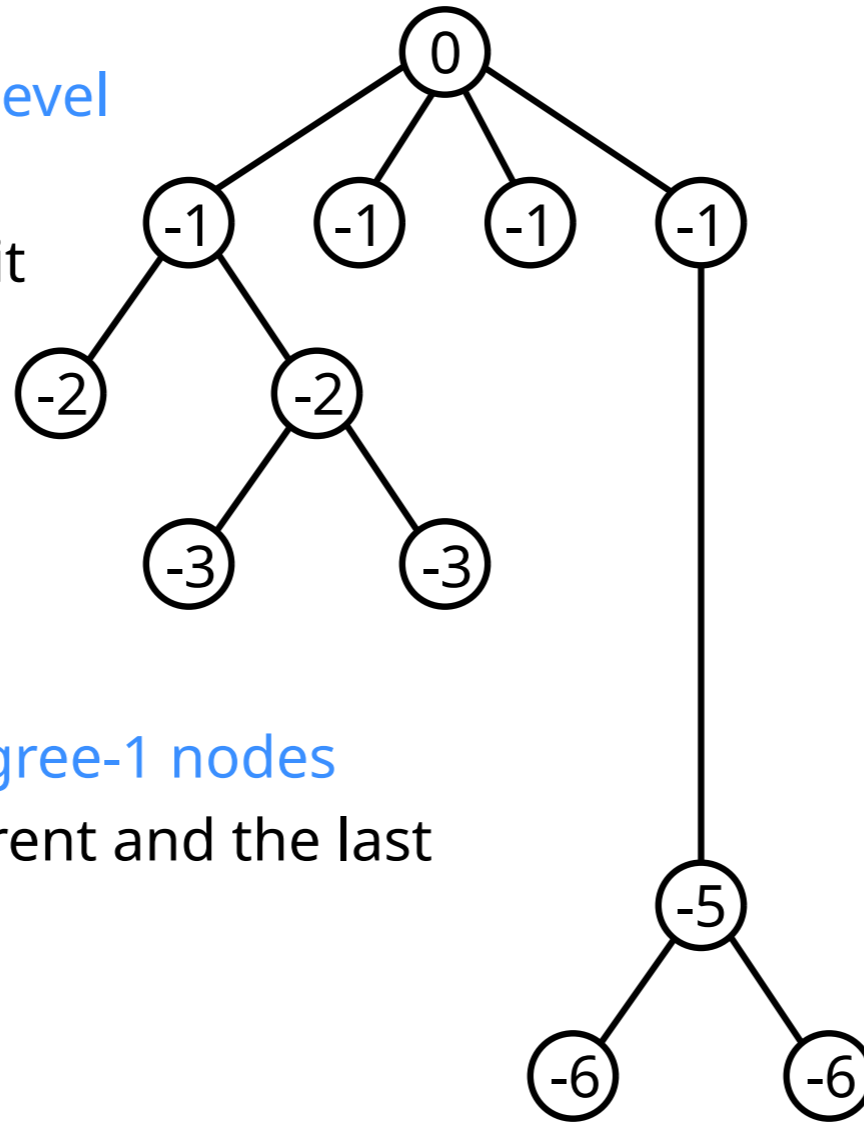
Paths consisting of only **degree-1 nodes**

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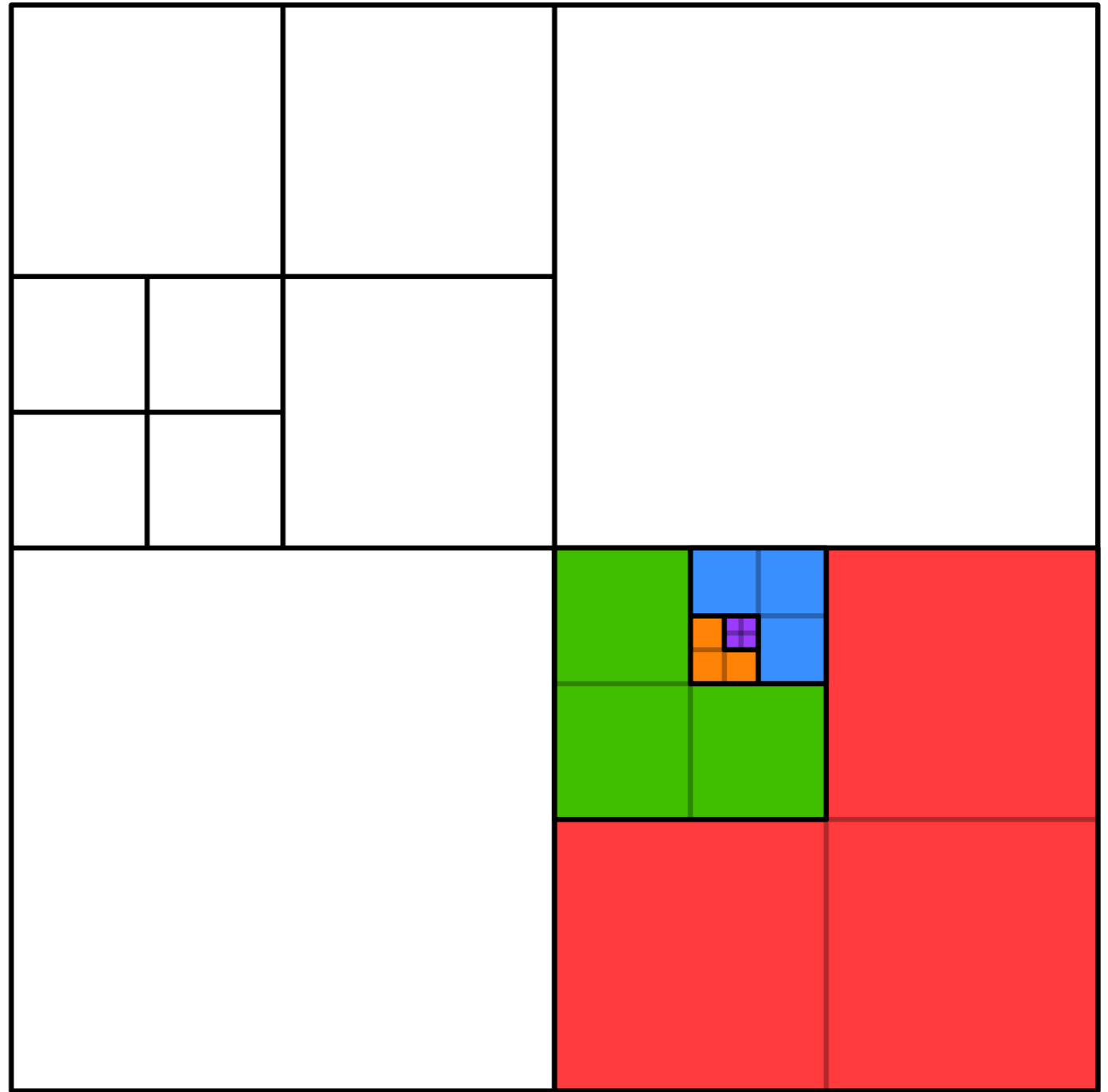
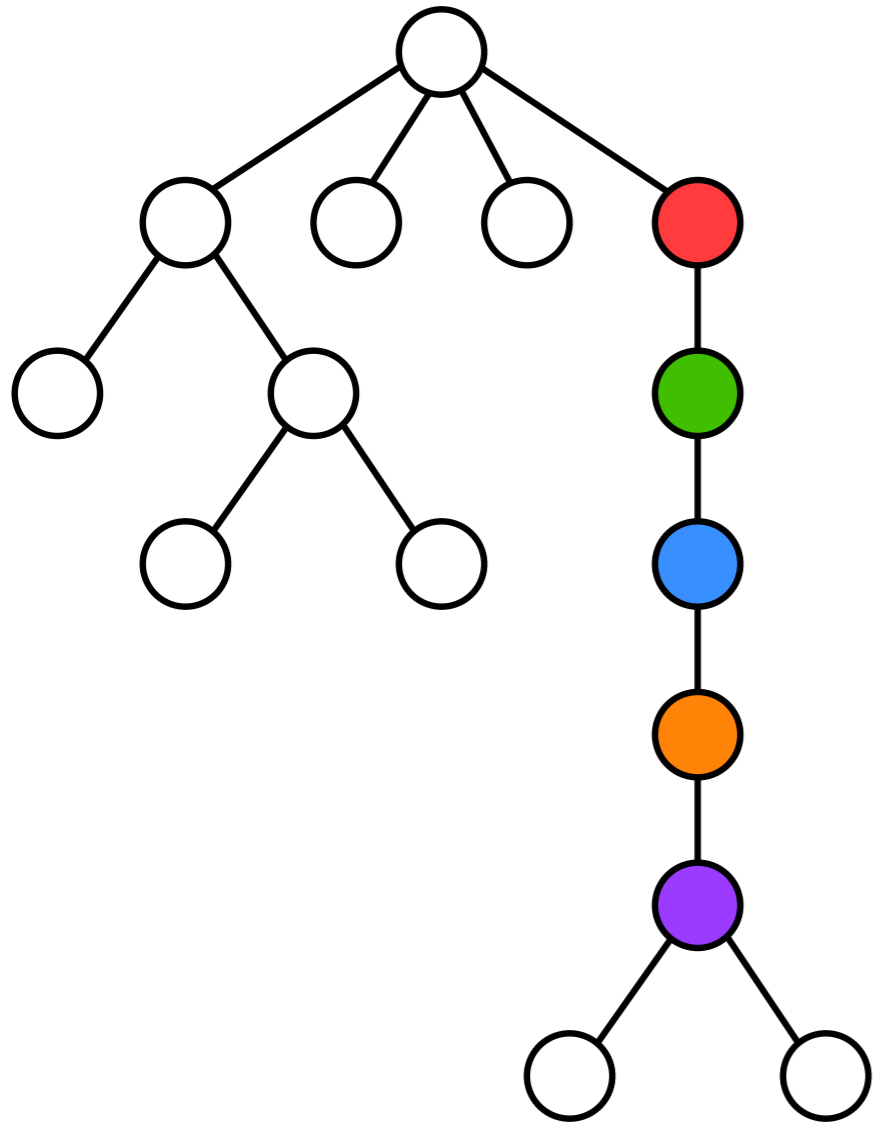
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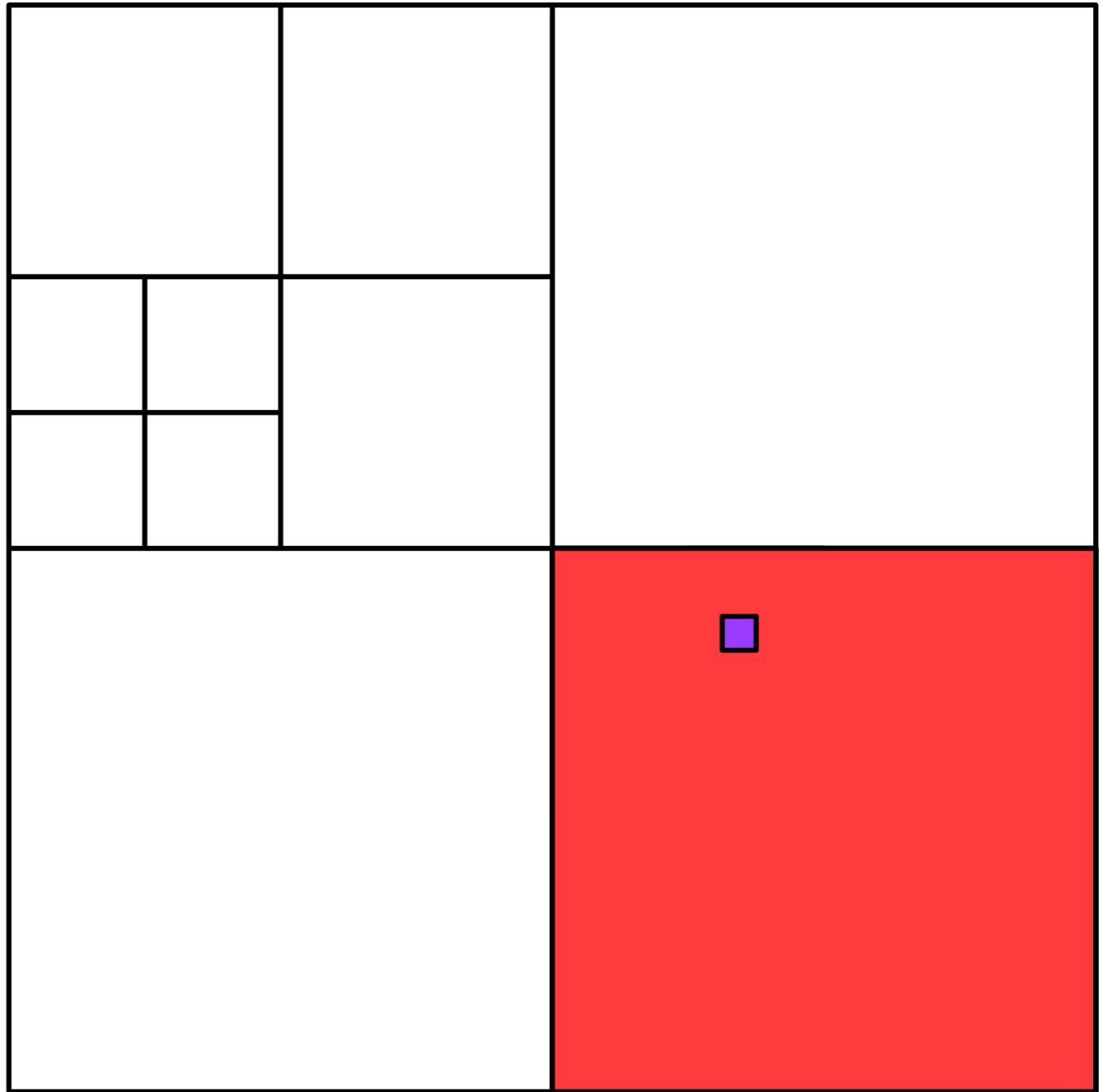
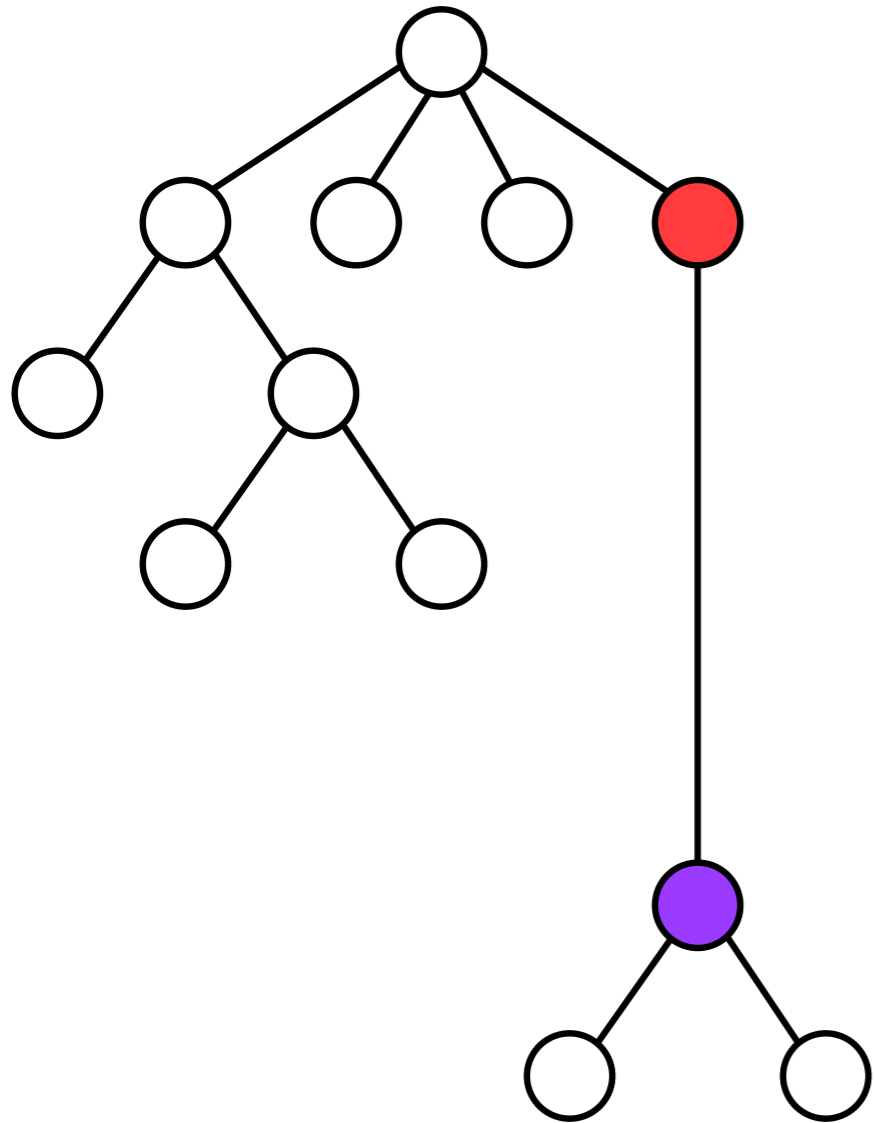
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# Merging squares



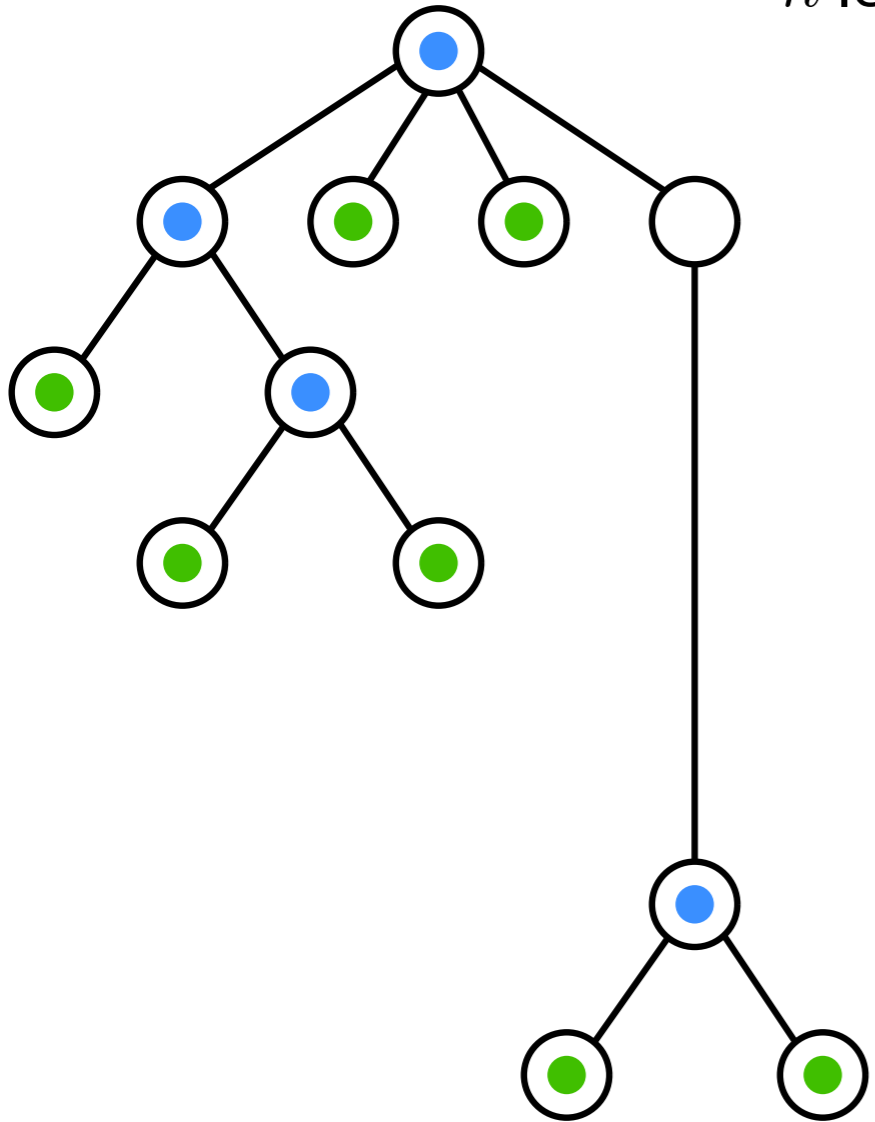
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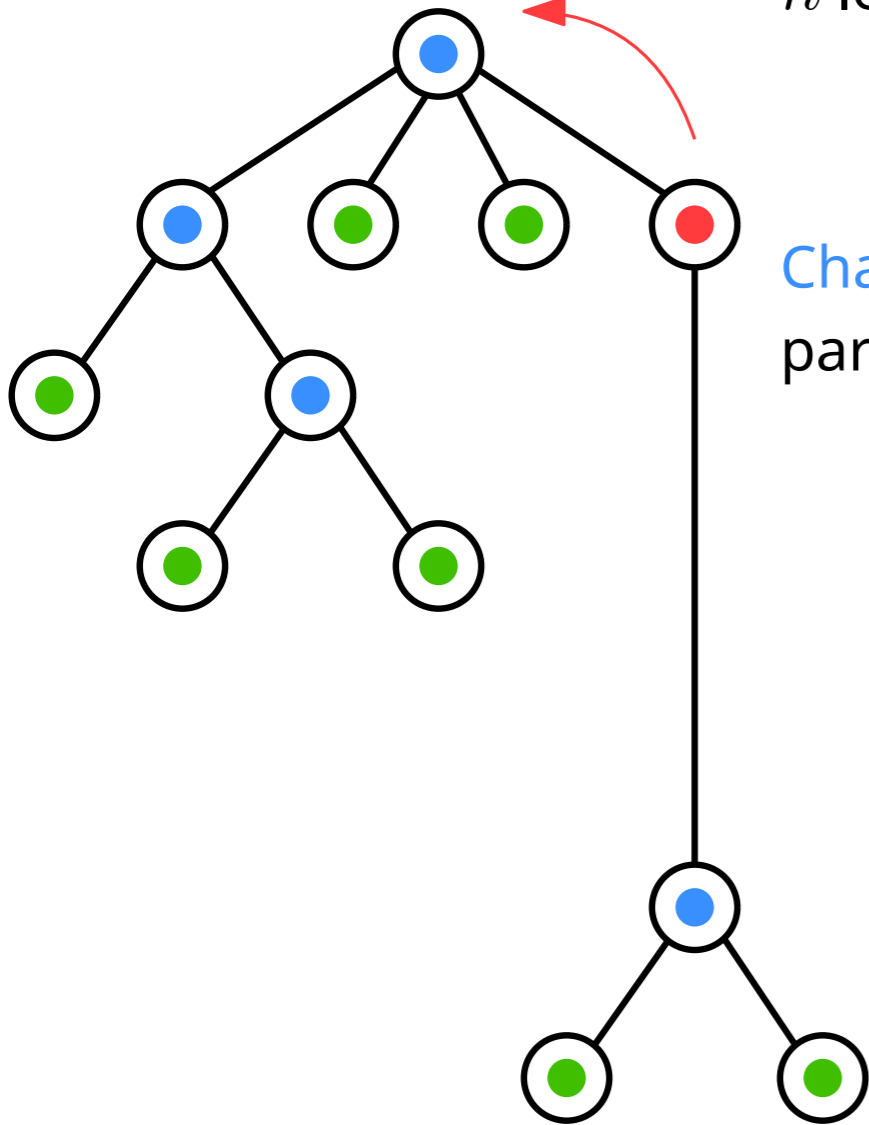
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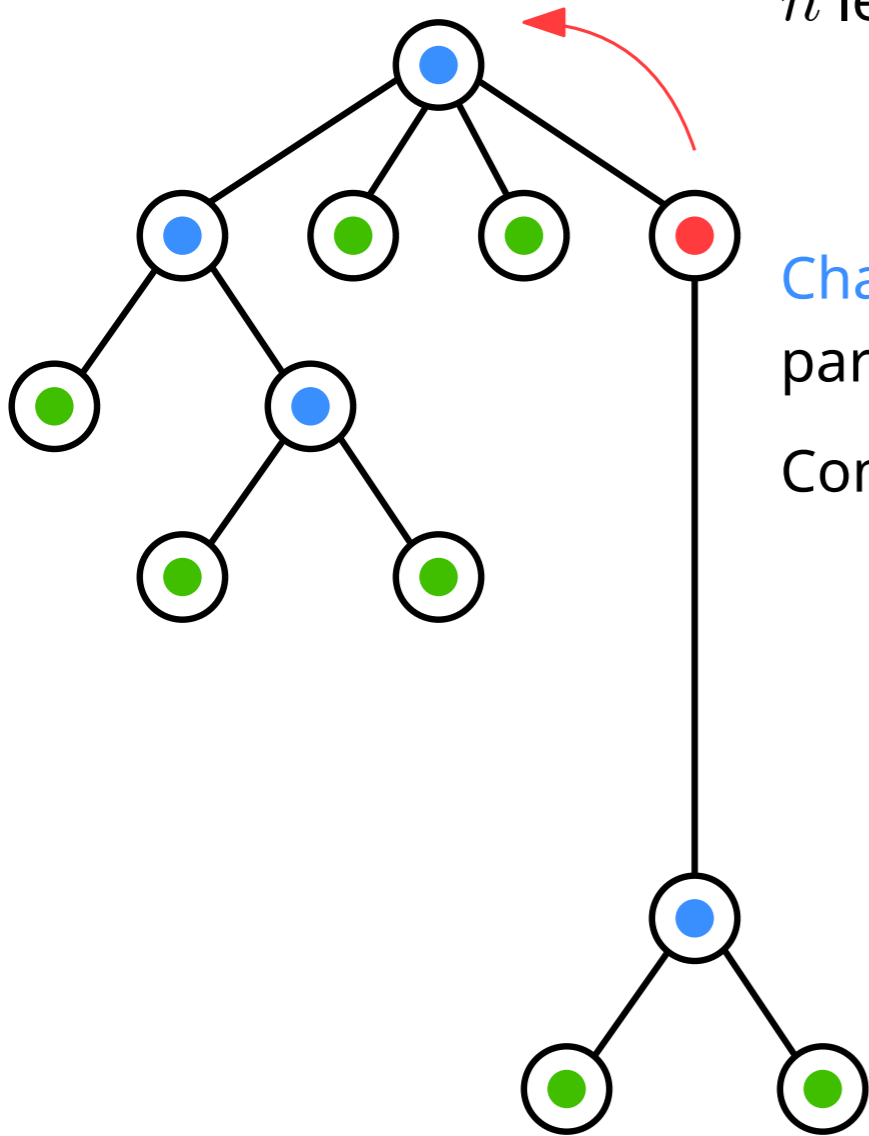
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Compressed quadtrees have **linear** size!

# Efficient construction

Simple recursive construction on compressed quadtrees has **unbounded** time complexity when the **spread** of the point set is unbounded.

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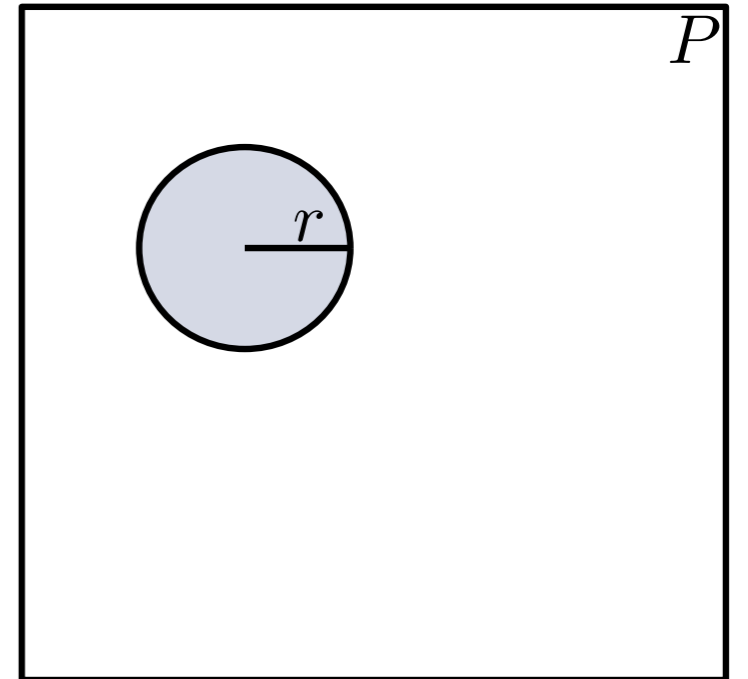
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**Question:** Which algorithm(s) do you know to compute this disk?

# Efficient construction

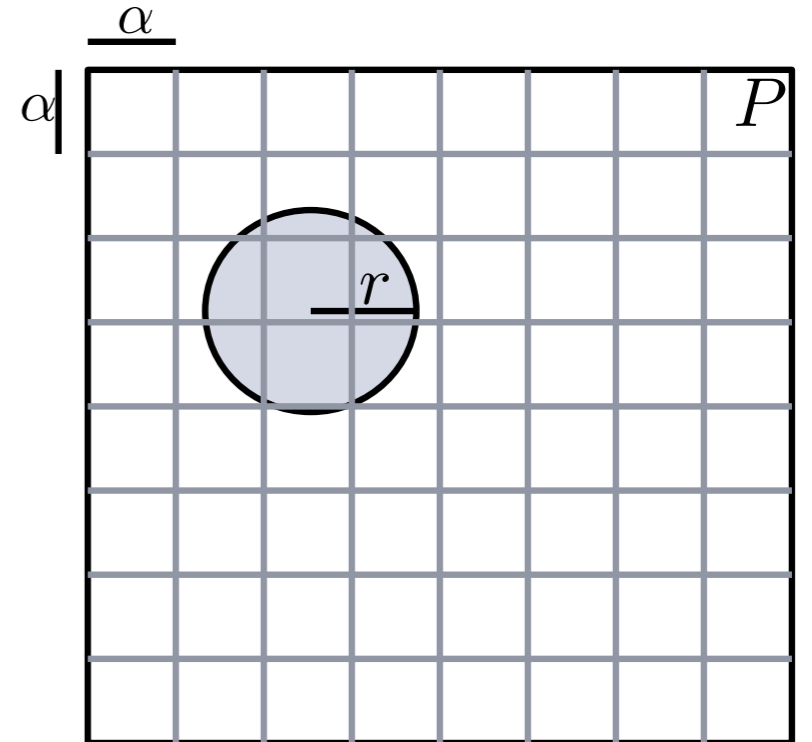
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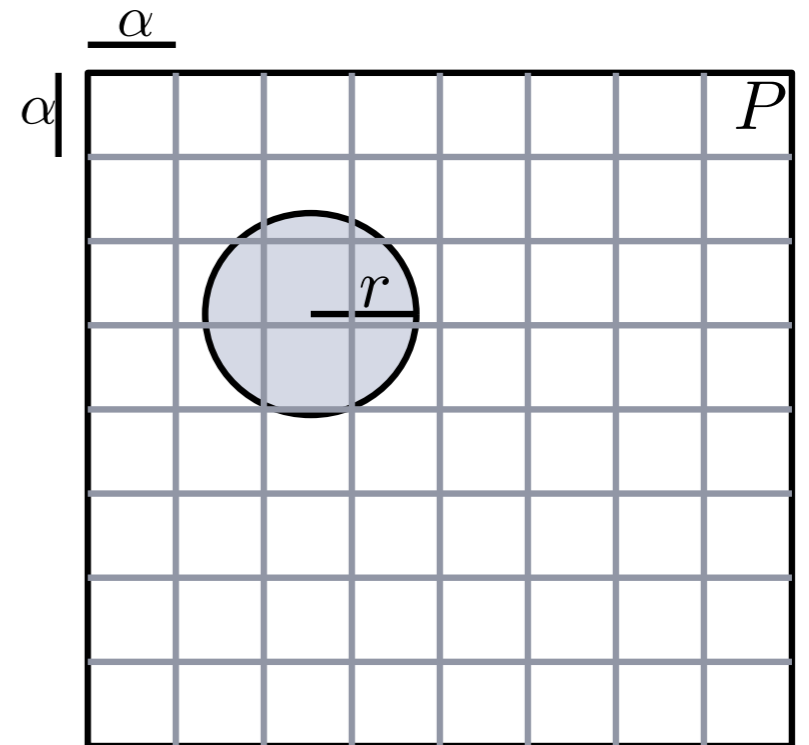
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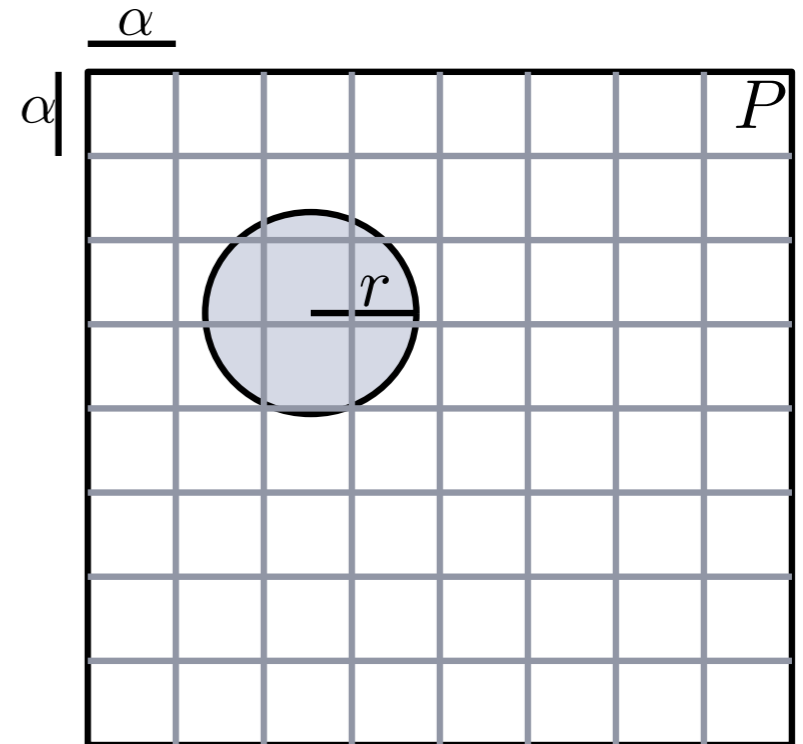
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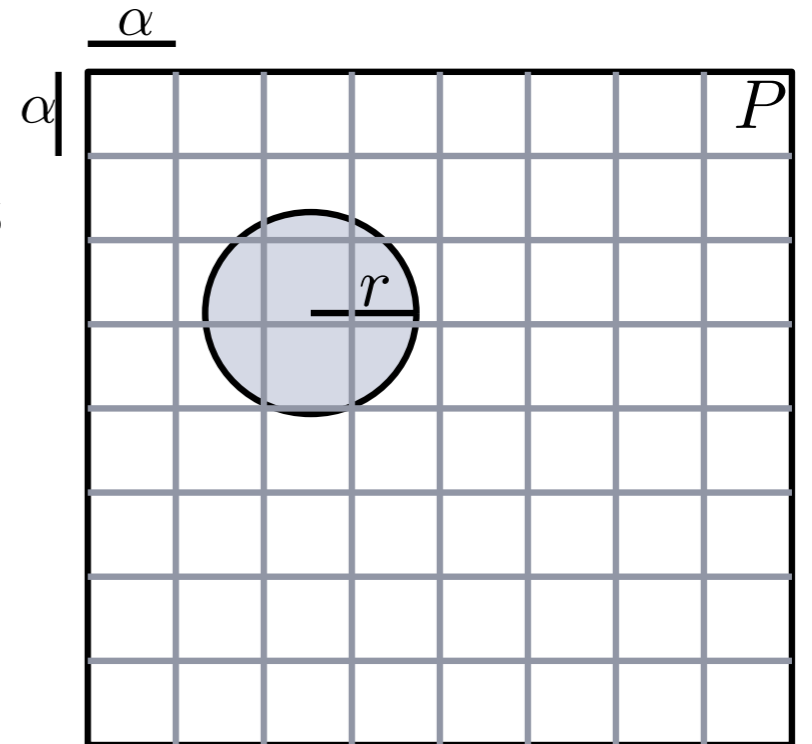
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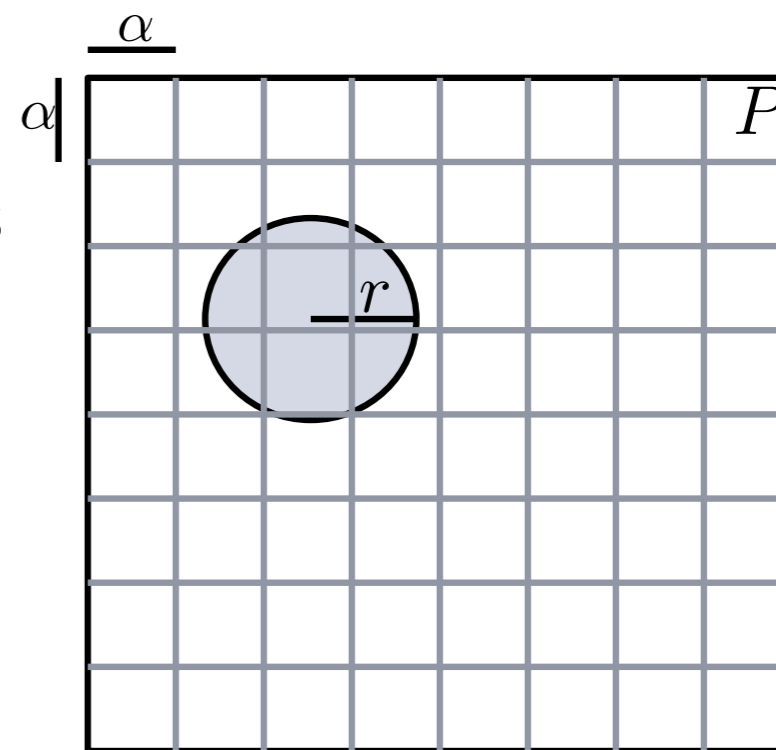
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Let  $\square$  denote the cell containing the largest number of points.

$$P_{in} = P \cap \square \text{ and } P_{out} = P \setminus P_{in}$$

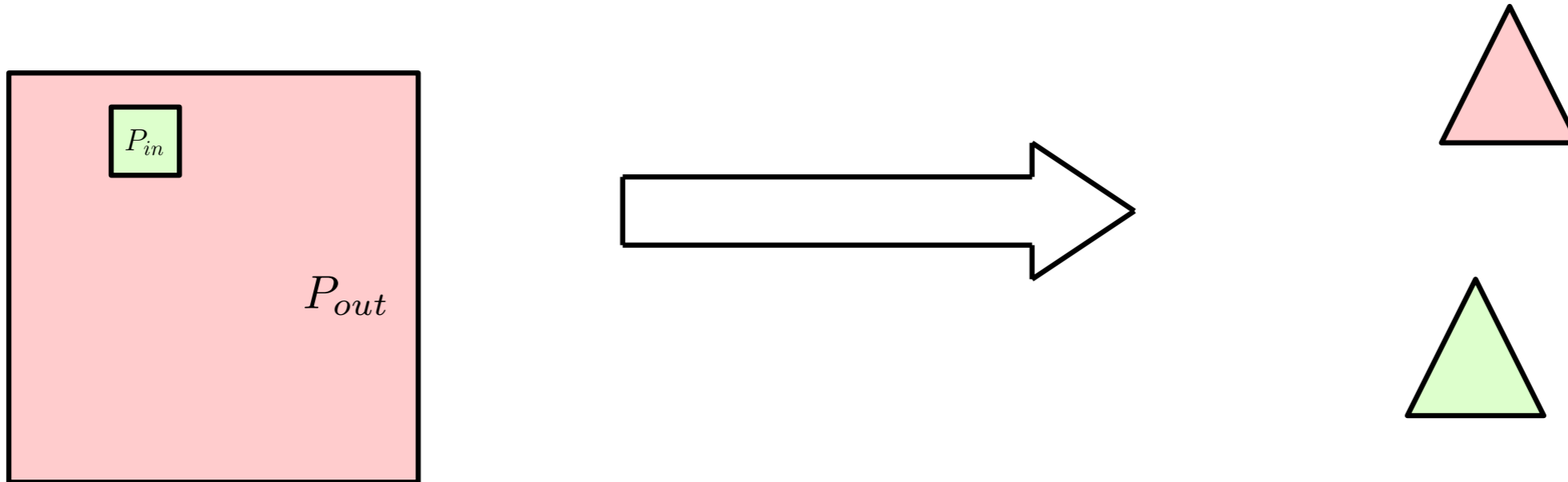
Note that  $|P_{in}| \geq n/250$  and  $|P_{out}| \geq n/2$



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Recursively construct quadtrees for  $P_{in}$  and  $P_{out}$



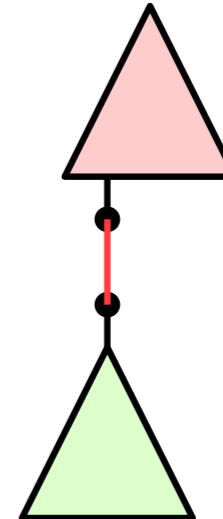
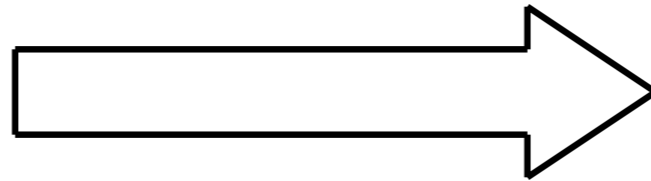
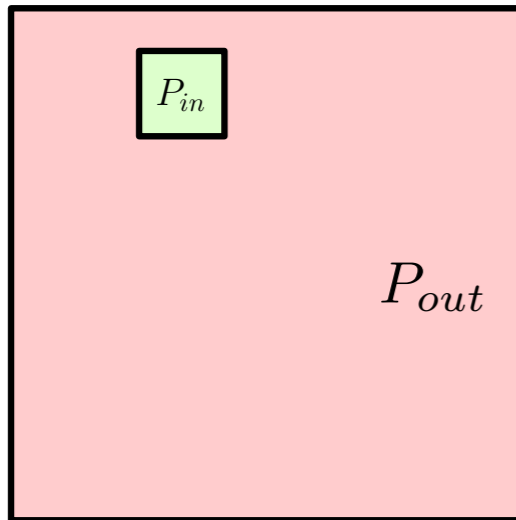


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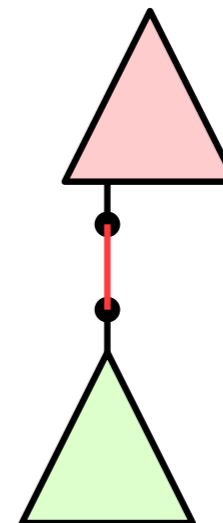
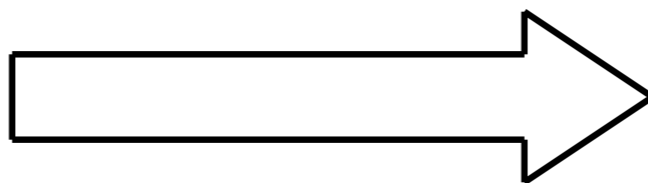
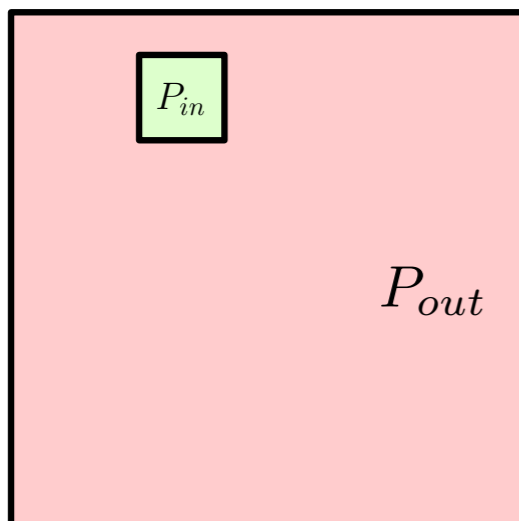


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$$\text{Construction time: } T(n) = O(n) + T(|P_{in}|) + T(|P_{out}|) = O(n \log n)$$

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What is the maximum depth that a quadtree on  $n$  points can have?

A  $\Theta(\log n)$

B  $\Theta(\sqrt{n})$

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**Question:** How does such a quadtree look like?

# Point-location on compressed quadtrees

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Alternative: preprocess  $T$  into a **balanced** tree  $T'$  with cross-pointers to  $T$ .

# Fast point-location - Fingering the quadtree

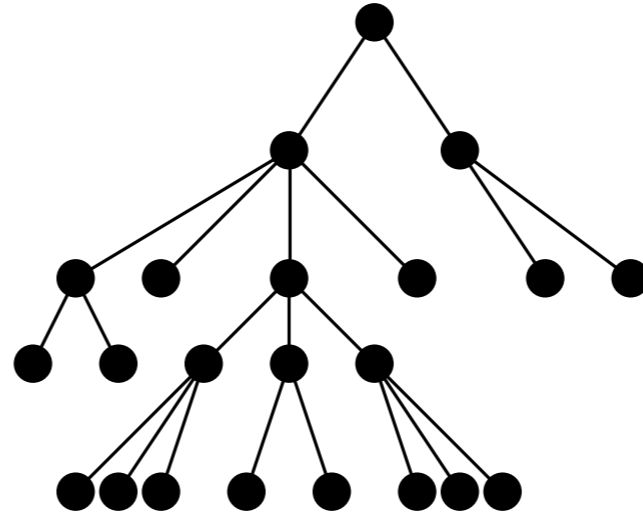
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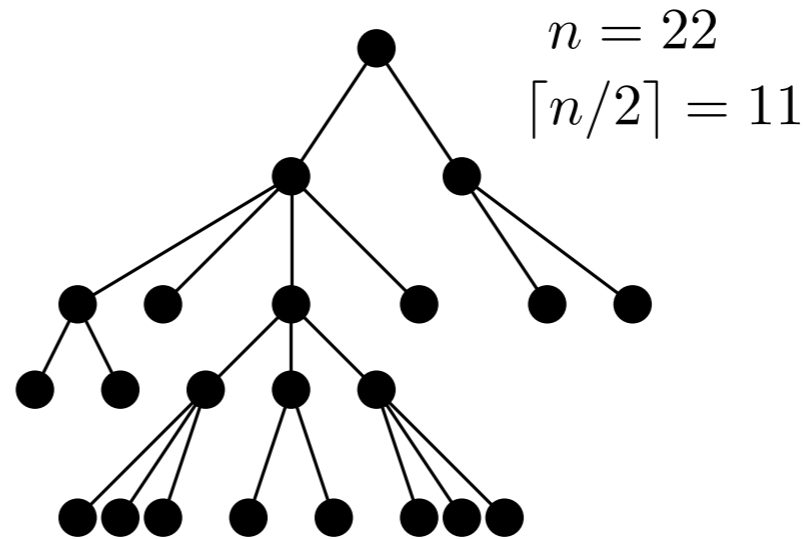


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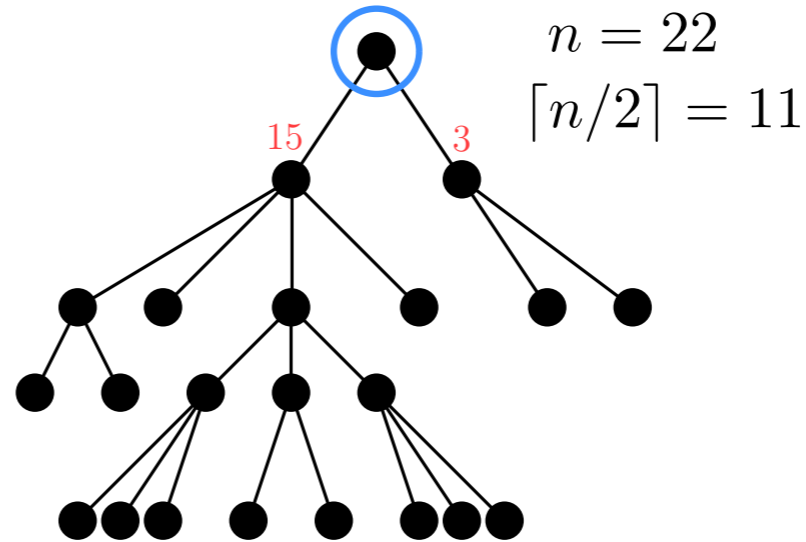


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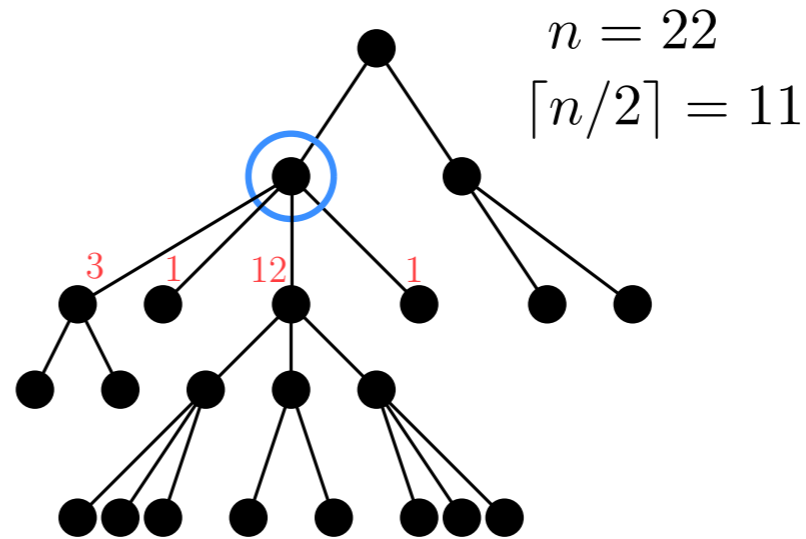


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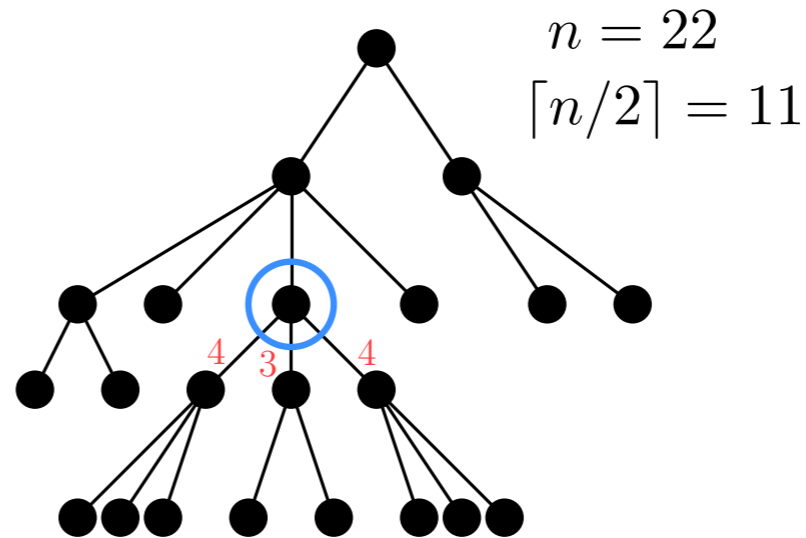


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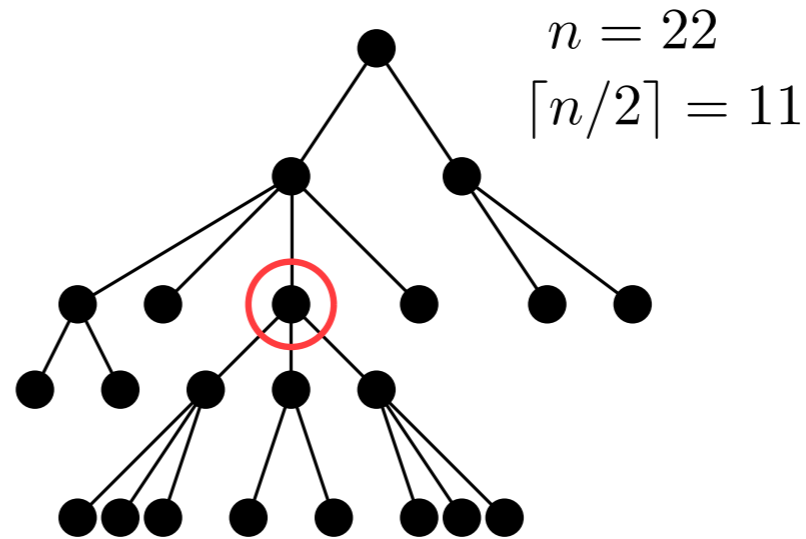


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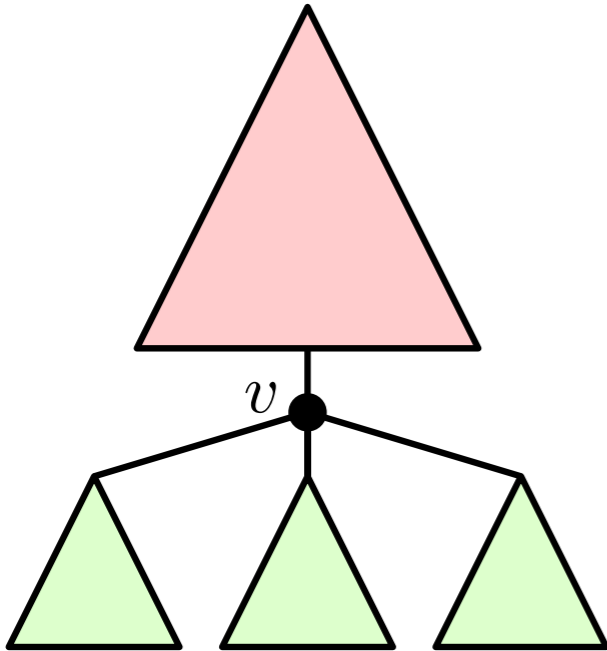
Once we get stuck:

- child subtree sizes  $< \lceil n/2 \rceil$
- rooted subtree size  $\leq n - \lceil n/2 \rceil \leq \lfloor n/2 \rfloor$

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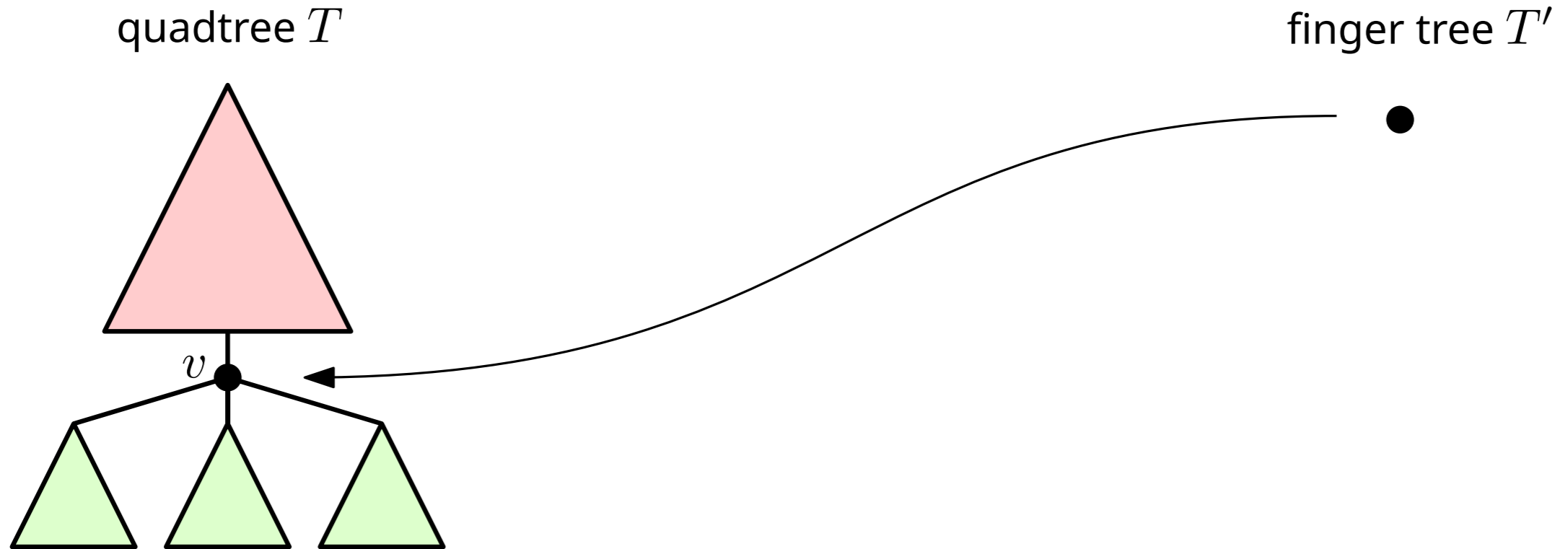
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quadtree  $T$



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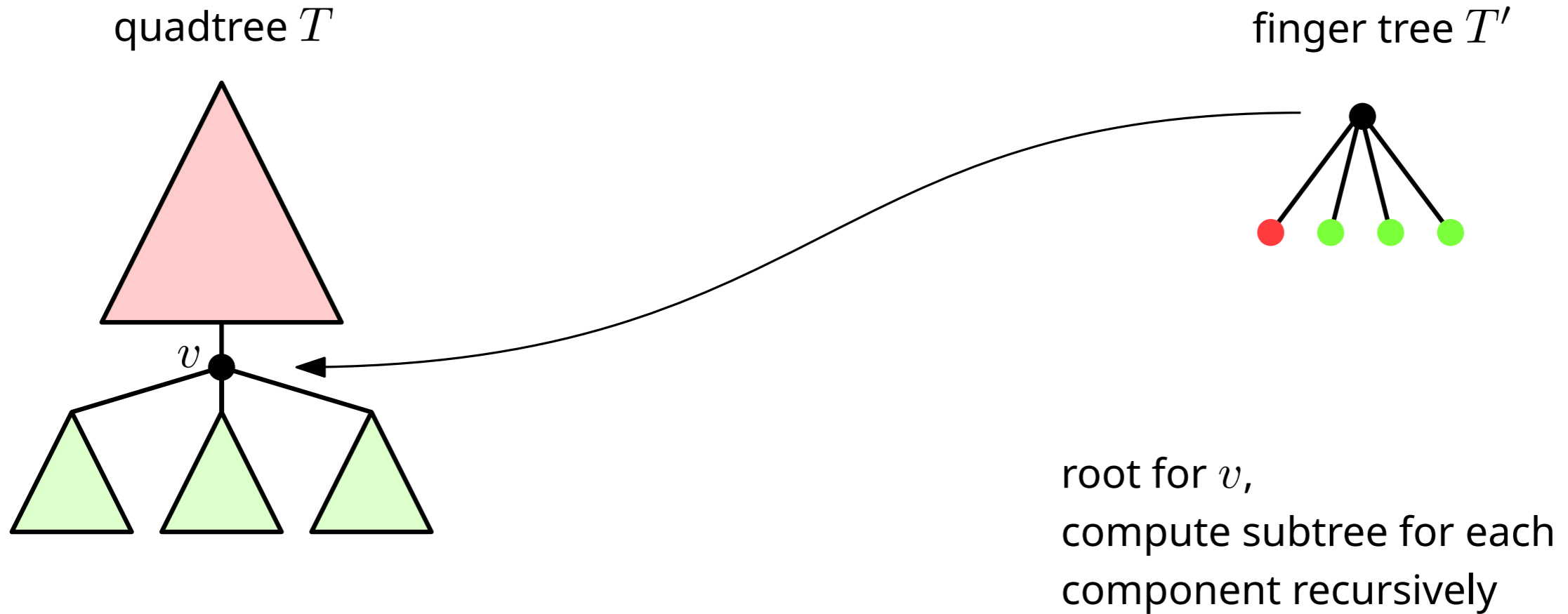
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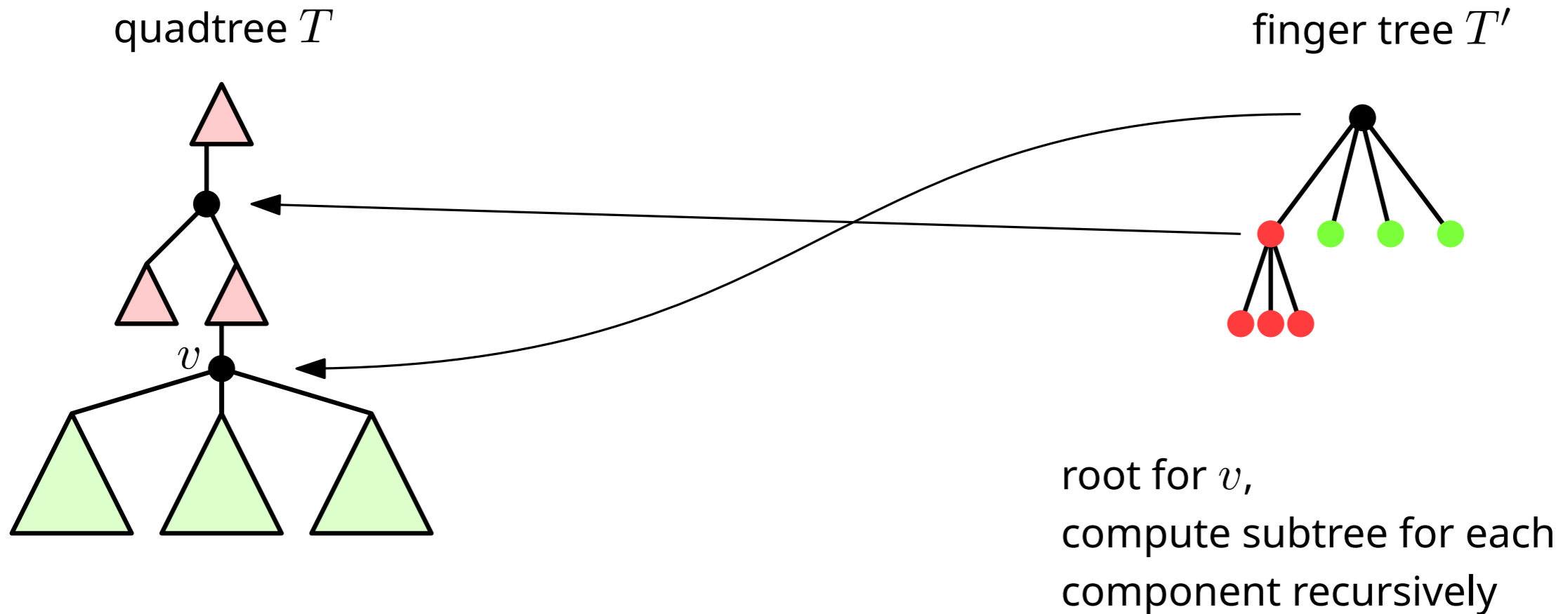
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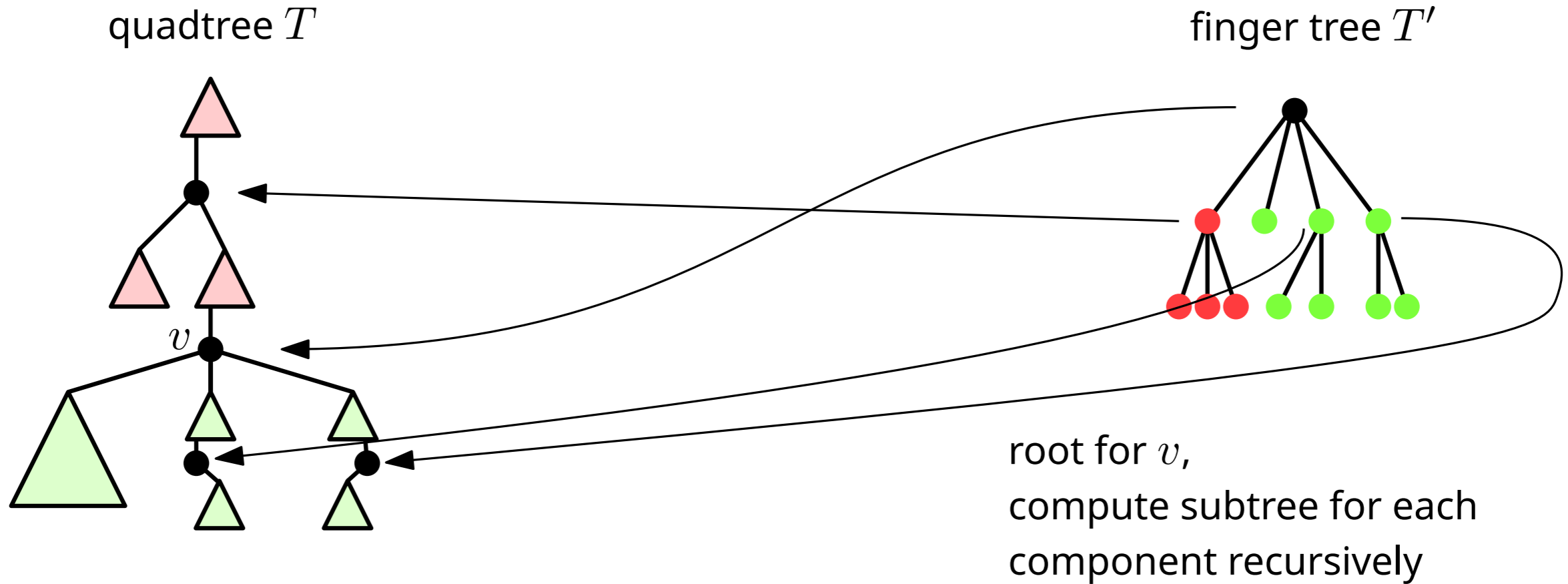
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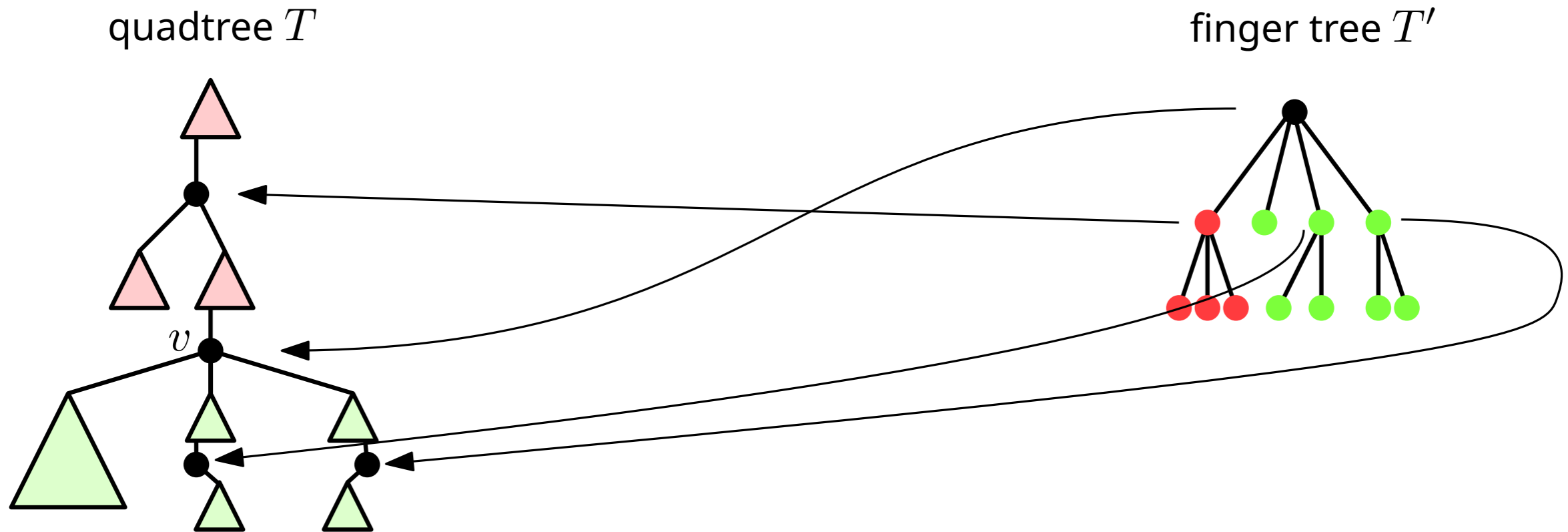
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To **query** for point  $q$ , recursively, in time  $O(\text{height of } T')$ :

- go into red subtree if  $q \notin \square_v$
- search all  $O(1)$  green subtrees if  $q \in \square_v$

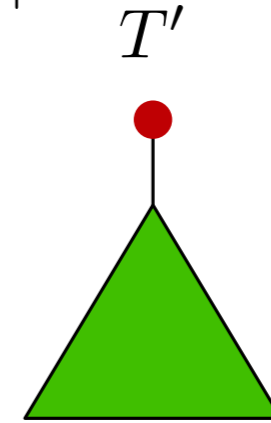
What are the **height/query time** and the **construction time** of the finger tree?

# Finger trees

Recall that the **separator** splits  $T$  into subtrees of size  $\leq \lceil n/2 \rceil$

recurrence for **height**:

$$\implies H(n) \leq 1 + H(\lceil n/2 \rceil) = O(\log n)$$

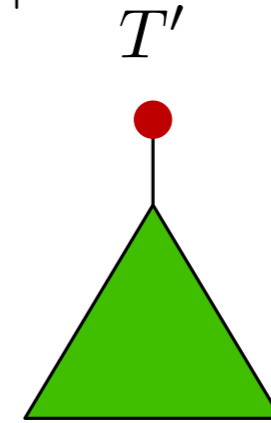


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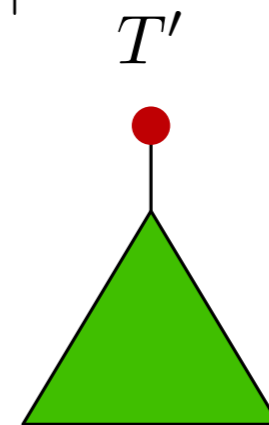


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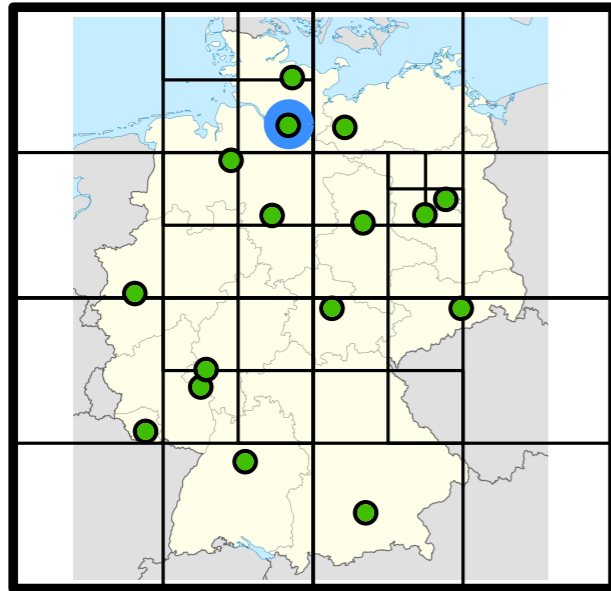
**Construction time**  $T(n) = O(n) + \sum_{i=1}^t T(n_i)$  where  $n_1 \dots n_t$  are the sizes of the  $t$  subtrees formed after removing the separator.

Since  $t = O(1)$  and  $n_i \leq \lceil n/2 \rceil$ , we have  $T(n) = O(n \log n)$



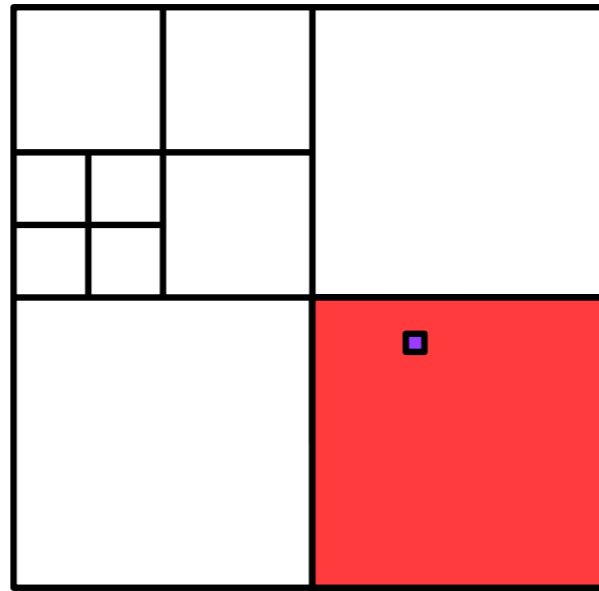
# Summary

Normal quadtrees



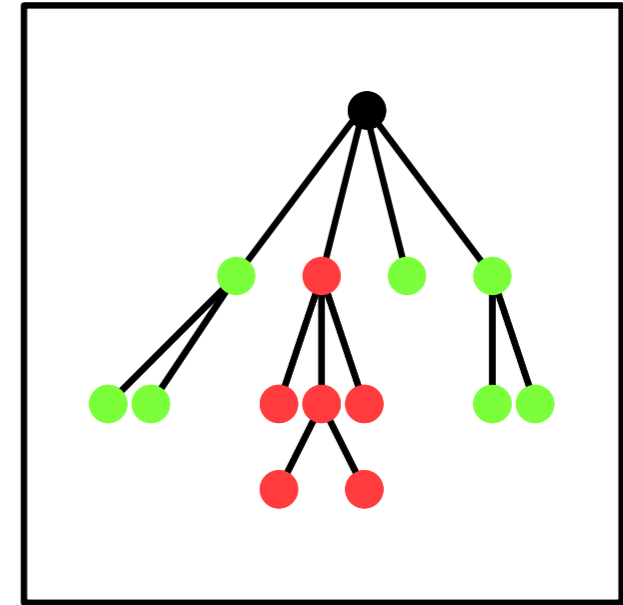
Bounded by spread

Compressed quadtrees



Bounded by number of points

Finger trees



Fast query time

more in book: [dynamic](#) quadtrees